Name:

| Question: | 1 | 2 | 3 | 4 | Total |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Points: | 30 | 10 | 40 | 20 | 100 |
| Score: |  |  |  |  |  |


| Question: | 1 | 2 | 3 | 4 | Total |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Bonus Points: | 10 | 10 | 0 | 0 | 20 |
| Score: |  |  |  |  |  |

Question 1.......................................................................................... 30 point
A matrix $U$ is called unitary iff

$$
U U^{*}=I
$$

where $U^{*}$ denotes the transpose of $U$ and $I$ is the identity matrix. A matrix $A$ is called antisymmetric iff

$$
A^{*}=-A
$$

(a) (10 points) Show that if $U$ is unitary then

$$
\operatorname{det} U= \pm 1
$$

(b) (10 points) Show that if $A$ is antisymmetric than $U=\exp (A)$ is unitary.
(c) (10 points) Show that if $A$ is antisymmetric and $P(t)$ is a solution of

$$
\dot{P}(t)=A P(t)
$$

with $P(0)=I$ then $P(t)$ is unitary for every $t$.
(d) (10 points (bonus)) Suppose now that $P(t)$ is a solution of the equation

$$
\dot{P}(t)=A(t) P(t)
$$

with $P(0)=I$ and $A(t)$ antisymmetric for every $t$. Show that $P(t)$ is unitary for every $t$. (Hint: consider $O(t)=P(t) P(t)^{*}$. Show that, if $P(t)$ is unitary than $\dot{O}(t)=0$.)

Consider the systems of equations

$$
\left\{\begin{array}{l}
\dot{x_{1}}=a x_{1}+x_{2}+x_{1}\left(x_{1}^{2}+x_{2}^{2}\right)  \tag{1}\\
\dot{x_{2}}=-x_{1}+a x_{2}+x_{2}\left(x_{1}^{2}+x_{2}^{2}\right)
\end{array}\right.
$$

with $a \leq 0$, and

$$
\left\{\begin{array}{l}
\dot{x_{1}}=b x_{1}+x_{2}  \tag{2}\\
\dot{x_{2}}=-x_{1}+b x_{2}
\end{array}\right.
$$

with $b \leq 0$.
(a) (10 points) For which values of $a$ and $b$ are eq.(1) and eq.(2) locally conjugated around the point $X^{*}=(0,0)$ ? (Hint: linearize eq.(1) and then use the Theorems at page 168 and 66 of the book.)
(b) (10 points (bonus)) Is the conjugacy global? (Hint: eq.(1) has a periodic orbit around 0 for $a \leq 0$.)

Consider the differential equations:

$$
\left\{\begin{array}{l}
\dot{x_{1}}=1-\frac{x_{1}^{2}}{x_{1}^{2}+x_{2}^{2}}-B x_{2}  \tag{3}\\
\dot{x_{2}}=-\frac{x_{1} x_{2}}{x_{1}^{2}+x_{2}^{2}}+B x_{1}
\end{array}\right.
$$

where $B$ is a parameter.
(a) (10 points) Calling

$$
E(X)=x_{1}^{2}+x_{2}^{2}
$$

show that if $X(t)=\left(x_{1}(t), x_{2}(t)\right)$ is a solution of eq.(3) than $E(X(t))$ is constant in time, i.e. $\dot{E}(X(t))=0$.
(b) (10 points) write $\left(x_{1}, x_{2}\right)=(r \cos \theta, r \sin \theta)$ and rewrite eq.(3) as a system of equations for $r$ and $\theta$. Observe that, from point (a) the equation for $r$ is simply $\dot{r}=0$.
(c) (10 points) Consider the equation for $\theta$ with $B$ as a parameter and $r=1$. Find the fixed points as a function of $B$. Draw the bifurcation diagram and describe the bifurcations you encounter as $B$ varies.

Question 4........................................................................................... 20 point Consider the differential equation

$$
\dot{X}=\left(\begin{array}{cc}
1+a & a \\
-a & 1-a
\end{array}\right) X
$$

Write the general solution for every value of $a$.

