

## Math 1553 Worksheet §2.3, S2.4

### Solutions

1. True or false. If the statement is *always* true, answer True. Otherwise, answer False. In parts (a) and (b),  $A$  is an  $m \times n$  matrix and  $b$  is a vector in  $\mathbf{R}^m$ .
- a) If  $b$  is in the span of the columns of  $A$ , then the matrix equation  $Ax = b$  is consistent.
  - b) If  $Ax = b$  is inconsistent, then  $A$  does not have a pivot in every column.
  - c) If  $A$  is a  $4 \times 3$  matrix, then the equation  $Ax = b$  is inconsistent for some  $b$  in  $\mathbb{R}^4$ .

### Solution.

- a) True. Let the columns of  $A$  be  $v_1, \dots, v_n$ . Since  $b$  in  $\text{Span}\{v_1, \dots, v_n\}$ , this means  $b$  can be written as a linear combinations of these column vectors, so

$$x_1 v_1 + \dots + x_n v_n = b$$

for some scalars  $x_1, \dots, x_n$ . Therefore,  $Ax = b$  where  $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$ .

- b) False, for instance consider

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

This is an inconsistent system even though  $A$  has a pivot in each column.

- c) True. Any  $4 \times 3$  matrix  $A$  will have at most 3 pivots, so  $A$  cannot have a pivot in every row. For example, consider the augmented matrix  $(A \mid b)$  below.

$$\left( \begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right)$$

2. Let

$$A = \begin{pmatrix} 1 & 0 & 5 \\ -2 & 1 & -6 \\ 0 & 2 & 8 \end{pmatrix}, \quad b = \begin{pmatrix} 2 \\ -1 \\ 6 \end{pmatrix}.$$

Solve the matrix equation  $Ax = b$  and write your answer in parametric form.

**Solution.**

We translate the matrix equation into an augmented matrix, and row reduce it:

$$\left( \begin{array}{ccc|c} 1 & 0 & 5 & 2 \\ -2 & 1 & -6 & -1 \\ 0 & 2 & 8 & 6 \end{array} \right) \xrightarrow{\text{rref}} \left( \begin{array}{ccc|c} 1 & 0 & 5 & 2 \\ 0 & 1 & 4 & 3 \\ 0 & 0 & 0 & 0 \end{array} \right)$$

The right column is not a pivot column, so the system is consistent.

The RREF of the augmented matrix gives

$$x_1 = 2 - 5x_3 \quad x_2 = 3 - 4x_3 \quad x_3 = x_3 \quad (x_3 \text{ is free}).$$

If we wanted to write just one specific solution, we could take  $x_3 = 0$  and that would give us  $x_1 = 2, x_2 = 3$ :

$$b = \begin{pmatrix} 2 \\ -1 \\ 6 \end{pmatrix} = 2 \begin{pmatrix} 1 \\ -2 \\ 0 \end{pmatrix} + 3 \begin{pmatrix} 0 \\ 1 \\ 2 \end{pmatrix} + 0 \begin{pmatrix} 5 \\ -6 \\ 8 \end{pmatrix}.$$

3. Find the set of solutions to  $x_1 - 3x_2 + 5x_3 = 0$ . Next, find the set of solutions to  $x_1 - 3x_2 + 5x_3 = 3$ . In each case, write your solution in parametric vector form. How do the solution sets compare geometrically?

### Solution.

The homogeneous system  $x_1 - 3x_2 + 5x_3 = 0$  corresponds to the augmented matrix  $(1 \ -3 \ 5 \ | \ 0)$ , which has two free variables  $x_2$  and  $x_3$ .

$$x_1 = 3x_2 - 5x_3 \quad x_2 = x_2 \text{ (free)} \quad x_3 = x_3 \text{ (free)}.$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3x_2 - 5x_3 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3x_2 \\ x_2 \\ 0 \end{pmatrix} + \begin{pmatrix} -5x_3 \\ 0 \\ x_3 \end{pmatrix} = \boxed{x_2 \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} -5 \\ 0 \\ 1 \end{pmatrix}}.$$

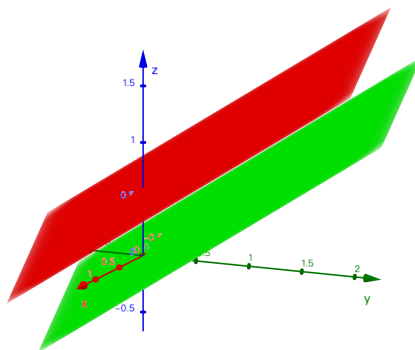
The solution set for  $x_1 - 3x_2 + 5x_3 = 0$  is the plane spanned by  $\begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} -5 \\ 0 \\ 1 \end{pmatrix}$ .

The nonhomogeneous system  $x_1 - 3x_2 + 5x_3 = 3$  corresponds to the augmented matrix  $(1 \ -3 \ 5 \ | \ 3)$  which has two free variables  $x_2$  and  $x_3$ .

$$x_1 = 3 + 3x_2 - 5x_3 \quad x_2 = x_2 \quad x_3 = x_3.$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3 + 3x_2 - 5x_3 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix} + \begin{pmatrix} 3x_2 \\ x_2 \\ 0 \end{pmatrix} + \begin{pmatrix} -5x_3 \\ 0 \\ x_3 \end{pmatrix} = \boxed{\begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix} + x_3 \begin{pmatrix} -5 \\ 0 \\ 1 \end{pmatrix}}.$$

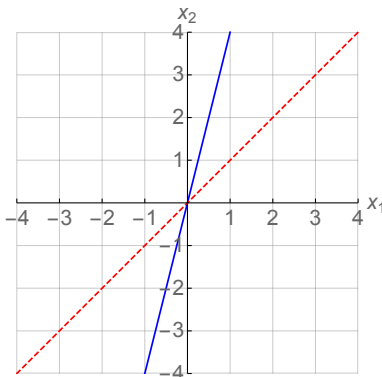
This solution set (red) is the *translation* by  $\begin{pmatrix} 3 \\ 0 \\ 0 \end{pmatrix}$  of the plane (green) spanned by  $\begin{pmatrix} 3 \\ 1 \\ 0 \end{pmatrix}$  and  $\begin{pmatrix} -5 \\ 0 \\ 1 \end{pmatrix}$ .



Here is the link to a 3D picture you can play with <https://www.geogebra.org/calculator/j57ttsnb>

4. Let  $A = \begin{pmatrix} 1 & -1 \\ 4 & -4 \end{pmatrix}$ . Draw the span of the columns of  $A$ , and draw the set of solutions to  $Ax = 0$ . Clearly label each.

**Solution.**



The **blue** line is the span of columns of  $A$ :  $\text{Span} \left\{ \begin{pmatrix} 1 \\ 4 \end{pmatrix} \right\}$ . If you draw the two column vectors, you will see they both fall on the line  $x_2 = 4x_1$ .

The **red** dashed line is the span of solutions of  $Ax = 0$ :  $\text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right\}$ . To see this is the case, you can row reduce the augmented matrix to RREF, which is  $\left( \begin{array}{cc|c} 1 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right)$ . That implies the solution set is the line  $x_2 = x_1$ .

5. Write an augmented matrix corresponding to a system of two linear equations in the three variables  $x_1, x_2, x_3$ , so that the solution set is the span of  $\begin{pmatrix} -4 \\ 1 \\ 0 \end{pmatrix}$ .

**Solution.**

We are asked to come up with a system whose solution set is the prescribed span, rather than being handed a system and discovering its solution set.

Since the span of any vector includes the origin, the zero vector is a solution, so the system is homogeneous.

Note that the span of  $\begin{pmatrix} -4 \\ 1 \\ 0 \end{pmatrix}$  is all vectors of the form  $t \begin{pmatrix} -4 \\ 1 \\ 0 \end{pmatrix}$  where  $t$  is real.

It consists of all  $\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$  so that  $x_1 = -4x_2$ ,  $x_2 = x_2$ ,  $x_3 = 0$ .

The equation  $x_1 = -4x_2$  gives  $x_1 + 4x_2 = 0$ , so one line in the matrix can be  $(1 \ 4 \ 0 \mid 0)$ .

The equation  $x_3 = 0$  translates to  $(0 \ 0 \ 1 \mid 0)$ . Note that this leaves  $x_2$  free, as desired.

This gives us the augmented matrix

$$\boxed{\begin{pmatrix} 1 & 4 & 0 & \mid & 0 \\ 0 & 0 & 1 & \mid & 0 \end{pmatrix}}.$$

(Multiple examples are possible. For example do an arbitrary row operation on the above matrix, that will also work.)