

Math 4305 Andrew

- Instructions:
1. You may use your text by Strang and one sheet of notes. Calculators may also be used.
 2. Show your work and explain your answers and reasoning.
 3. Do any 6 of the 7 problems. Clearly indicate the problem you *do not want graded* on the table below.

1. (25) Find all values of the parameter a for which the following system of equations has a solution.

$$\begin{aligned}x + 3y + 3z &= 1 \\x + y + 6z &= a \\-x + y - 9z &= a\end{aligned}$$

2. (25) A matrix \mathbf{A} is said to be *skew-symmetric* if $\mathbf{A}^T = -\mathbf{A}$. Exhibit a basis for the vector space of all n by n skew-symmetric matrices and calculate the dimension of this vector space.

3. (25) Let P denote the plane spanned by the vectors $\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$ and $\begin{pmatrix} 3 \\ 2 \\ 0 \end{pmatrix}$.

- a. Determine the matrix \mathbf{R} for the orthogonal projection onto P .
- b. Determine the matrix \mathbf{H} for the (orthogonal) reflection across P .

4. (25) Calculate the eigenvalues and eigenvectors of $\mathbf{A} = \begin{pmatrix} 1 & 0 & 1 \\ -2 & 2 & 2 \\ -1 & 0 & 3 \end{pmatrix}$. Is \mathbf{A} similar to a diagonal matrix?

5. (25) On the first hour test we saw that for every n by n matrix \mathbf{A} , there is a polynomial $q(x)$ of degree at most n^2 such that $q(\mathbf{A}) = \mathbf{0}$ (the identically 0 matrix). We later proved the Cayley-Hamilton Theorem, which states that if \mathbf{A} is any n by n matrix, and p denotes its characteristic polynomial, then $p(\mathbf{A}) = \mathbf{0}$. The characteristic polynomial, or course, has degree n .

The *minimal polynomial* of \mathbf{A} is defined to be the polynomial m with leading coefficient 1 of smallest degree for which $m(\mathbf{A}) = \mathbf{0}$.

- a. Calculate the characteristic and minimal polynomials of $\mathbf{A} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \end{bmatrix}$.
- b. Prove that if \mathbf{A} and \mathbf{B} are similar matrices, then \mathbf{A} and \mathbf{B} have the same minimal polynomial.

6. (25) The *condition number* of a matrix \mathbf{A} is defined to be $c(\mathbf{A}) = \|\mathbf{A}\| \|\mathbf{A}^{-1}\|$, and it provides a measure of the sensitivity (inherent and due to round-off error) of $\mathbf{A} \mathbf{x} = \mathbf{b}$. Although the condition number is usually only estimated, in this problem we'll ask you to actually calculate two of them.

- a. Using $\|\mathbf{C}\|_2$ for all matrices, show that the condition number of any orthogonal matrix is 1.
- b. The n by n *Hilbert matrix* arises from the normal equations for least-squares polynomial approximation, and is given by $\mathbf{H} = (h_{i,j})$ with
- $$h_{i,j} = \frac{1}{i+j-1}, \quad 1 \leq i, j \leq n.$$

Write down the 4 by 4 Hilbert matrix, and compute its condition number, using $\|\mathbf{C}\|_2$ for all matrices. The inverse of this matrix is

$$\begin{bmatrix} 16 & -120 & 240 & -140 \\ -120 & 1200 & -2700 & 1680 \\ 240 & -2700 & 6480 & -4200 \\ -140 & 1680 & -4200 & 2800 \end{bmatrix}.$$

7. (25) Suppose $\mathbf{A} = (a_{i,j})$ is a matrix with $a_{i,j} > 0$ for all i,j , and $\mathbf{v} = \begin{pmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{pmatrix}$ is a nonzero vector with $v_j > 0$ for all j . Show that all coordinates of $\mathbf{A}\mathbf{v}$ are strictly positive.

Answers

- The system has a solution if and only if $a = 1/3$.
- Let $\mathbf{B}_{i,j}$ be the n by n matrix with a 1 in position ij and -1 in position ji . Then the collection of matrices $\mathbf{B}_{i,j}$ with $i < j$ is a basis for the space of skew-symmetric matrices. Thus the dimension is $\frac{n(n-1)}{2}$.
- $\mathbf{R} = \frac{1}{17} \begin{pmatrix} 13 & 6 & -4 \\ 6 & 8 & 6 \\ -4 & 6 & 13 \end{pmatrix}$, $\mathbf{H} = 2\mathbf{P} - \mathbf{I}$.
- $\lambda = 2, 2, 2$. Two linearly independent eigenvectors are $\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$, $\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$. The matrix is not diagonalizable.
- a. The characteristic polynomial is $(\lambda - 2)^3$. The minimal polynomial is $(\lambda - 2)^2$.
b. Start by showing that if $\mathbf{A} = \mathbf{S}^{-1}\mathbf{B}\mathbf{S}$, then $p(\mathbf{A}) = \mathbf{S}^{-1}p(\mathbf{B})\mathbf{S}$.
- a. If \mathbf{Q} is orthogonal, then $\|\mathbf{Q}\|_2 = \sqrt{\max \text{eigenvalue of } \mathbf{Q}^T\mathbf{Q}} = 1$ since $\mathbf{Q}^T\mathbf{Q} = \mathbf{I}$, and \mathbf{Q}^{-1} is also orthogonal.
b. Use the fact that $\|\mathbf{C}\|$ is the maximum absolute row sum of \mathbf{C} .
- Please see your class notes.