MATH 1553, C.J. JANKOWSKI MIDTERM 1

Name	Section	

Please **read all instructions** carefully before beginning.

- You have 50 minutes to complete this exam.
- There are no aids of any kind (calculators, notes, text, etc.) allowed.
- Please show your work unless specified otherwise. A correct answer without appropriate work may be given little or no credit.
- You may cite any theorem proved in class or in the sections we covered in the text.
- Good luck!

Scoring Page

Please do not write on this page.

1	2	3	4	5	Total

Problem 1.

a) C	Com	pute	3 -2 1	$\binom{2}{0}{\binom{1}{-3}}$					
b) If	b) If <i>A</i> is a 2 × 3 matrix with 2 pivots, then the set of solutions to $Ax = 0$ is a:								
		(circ	le on	e answer)	point	line	2-pla	ane	3-plane
	in:								
				(circle one	answer)	R	\mathbf{R}^2	\mathbf{R}^3 .	
Y	True or false. Circle T if the statement is always true, and circle F otherwise. You do not need to justify your answer.								
	c)	Т	F	If a system of linear equations has more variables than equa- tions, then the system must have infinitely many solutions.					
(d)	Т	F	If A is an r then the ec	$n \times n$ matriquation Ax	rix and $A = b$ has	A has a s a solut	pivot in tion for	n every column, each b in \mathbf{R}^m .
(e)	Т	F	The three v	vectors $\begin{pmatrix} 1\\0\\0 \end{pmatrix}$	$\left(\begin{array}{c} 1\\ 1\\ 0 \end{array} \right)$, and $\left(\right)$	$\begin{pmatrix} -1\\0\\1 \end{pmatrix}$ sı	pan R ³ .
:	f)	Т	F	If u , v , and is \mathbf{R}^2 .	w are noi	nzero ve	ctors in	\mathbf{R}^2 , the	en Span{ <i>u</i> , <i>v</i> , <i>w</i> }

Solution.

a)
$$1 \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix} - 3 \begin{pmatrix} 2 \\ 0 \\ 4 \end{pmatrix} = \begin{pmatrix} 3 \\ -2 \\ 1 \end{pmatrix} + \begin{pmatrix} -6 \\ 0 \\ -12 \end{pmatrix} = \begin{pmatrix} -3 \\ -2 \\ -11 \end{pmatrix}.$$

- **b)** Line in \mathbb{R}^3 . Since there are 2 pivots but 3 columns, one column will not have a pivot, so Ax = 0 will have exactly one free variable. The number of entries in *x* must match the number of columns of *A* (namely, 3), so each solution *x* is in \mathbb{R}^3 .
- c) False. The system can be inconsistent. For example: x + y + z = 5, x + y + z = 2.
- **d)** False. For example, if $A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$, then $Ax = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$ is inconsistent.
- e) True. The three vectors form a 3×3 matrix with a pivot in every row.
- **f)** False. Take $v_1 = v_2 = v_3 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$. Many other counterexamples possible.

Johnny Rico believes that the secret to the universe can be found in the system of two linear equations in x and y given by

$$x - y = h$$
$$3x + hy = 4$$

where h is a real number.

- **a)** Find all values of *h* (if any) which make the system inconsistent. Briefly justify your answer.
- **b)** Find all values of *h* (if any) which make the system have a unique solution. Briefly justify your answer.

Solution.

Represent the system with an augmented matrix and row-reduce:

$$\begin{pmatrix} 1 & -1 & | & h \\ 3 & h & | & 4 \end{pmatrix} \xrightarrow{R_2 - 3R_1} \begin{pmatrix} 1 & -1 & | & h \\ 0 & h + 3 & | & 4 - 3h \end{pmatrix}.$$

- a) If h = -3 then the matrix is $\begin{pmatrix} 1 & -1 & | & -3 \\ 0 & 0 & | & 13 \end{pmatrix}$, which has a pivot in the rightmost column and is therefore inconsistent.
- b) If $h \neq -3$, then the matrix has a pivot in each row to the left of the augment: $\begin{pmatrix} 1 & -1 & h \\ 0 & h+3 & 4-3h \end{pmatrix}$. The right column is not a pivot column, so the system is consistent. The left side has a pivot in each column, so the solution is unique.

a) Solve the system of equations by putting an augmented matrix into reduced row echelon form. Clearly indicate which variables (if any) are free variables.

$$\begin{aligned} x_1 + 2x_2 + 2x_3 - x_4 &= 4 \\ 2x_1 + 4x_2 + x_3 - 2x_4 &= -1 \\ -x_1 - 2x_2 - x_3 + x_4 &= -1 \end{aligned}$$

b) Write the set of solutions to

$$x_1 + 2x_2 + 2x_3 - x_4 = 0$$

$$2x_1 + 4x_2 + x_3 - 2x_4 = 0$$

$$-x_1 - 2x_2 - x_3 + x_4 = 0$$

in parametric vector form.

Solution.

a)

$$\begin{pmatrix} 1 & 2 & 2 & -1 & | & 4 \\ 2 & 4 & 1 & -2 & | & -1 \\ -1 & -2 & -1 & 1 & | & -1 \end{pmatrix} \xrightarrow{R_2 = R_2 - 2R_1} \begin{pmatrix} 1 & 2 & 2 & -1 & | & 4 \\ 0 & 0 & -3 & 0 & | & -9 \\ 0 & 0 & 1 & 0 & | & 3 \end{pmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{pmatrix} 1 & 2 & 2 & -1 & | & 4 \\ 0 & 0 & 1 & 0 & | & 3 \\ 0 & 0 & -3 & 0 & | & -9 \end{pmatrix}$$

$$\xrightarrow{R_3 = R_3 + 3R_2}_{R_1 = R_1 - 2R_2} \begin{pmatrix} 1 & 2 & 0 & -1 & | & -2 \\ 0 & 0 & 1 & 0 & | & 3 \\ 0 & 0 & 0 & 0 & | & 0 \end{pmatrix}$$

Therefore, x_2 and x_4 are free, and we have:

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$$x_1 = -2 - 2x_2 + x_4 \qquad x_2 = x_2 \qquad x_3 = 3 \qquad x_4 = x_4$$

b) If we had written the solution to part (a) in parametric vector form, it would be:

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} -2 - 2x_2 + x_4 \\ x_2 \\ 3 \\ x_4 \end{pmatrix} = \begin{pmatrix} -2 \\ 0 \\ 3 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}.$$

The equation in (b) is just the corresponding homogeneous equation, which is a translate of the above plane which includes the origin.

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = x_2 \begin{pmatrix} -2 \\ 1 \\ 0 \\ 0 \end{pmatrix} + x_4 \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix} \qquad (x_2, x_4 \text{ real})$$

The diagram below represents the temperature at points along wires, in celcius.



Let T_1 , T_2 , T_3 be the temperatures at the interior points. Assume the temperature at each interior point is the average of the temperatures of the three adjacent points.

- a) Write a system of three linear equations whose solution would give the temperatures T_1 , T_2 , and T_3 . Do not solve it.
- b) Write the system as a vector equation. Do not solve it.
- c) Write a matrix equation Ax = b that represents this system. Specify every entry of *A*, *x*, and *b*. Do not solve it.

Solution.

a) The left side system below or right-side system below are both fine.

$$T_{1} = \frac{T_{2} + T_{3} + 30}{3}, \text{ or } 3T_{1} - T_{2} - T_{3} = 30.$$

$$T_{2} = \frac{T_{1} + T_{3} + 60}{3}, \text{ or } -T_{1} + 3T_{2} - T_{3} = 60.$$

$$T_{3} = \frac{T_{1} + T_{2} + 90}{3}, \text{ or } -T_{1} - T_{2} + 3T_{3} = 90.$$
b)
$$T_{1} \begin{pmatrix} 3 \\ -1 \\ -1 \end{pmatrix} + T_{2} \begin{pmatrix} -1 \\ 3 \\ -1 \end{pmatrix} + T_{3} \begin{pmatrix} -1 \\ -1 \\ 3 \end{pmatrix} = \begin{pmatrix} 30 \\ 60 \\ 90 \end{pmatrix}.$$
c)
$$\begin{pmatrix} 3 & -1 & -1 \\ -1 & 3 & -1 \\ -1 & -1 & 3 \end{pmatrix} \begin{pmatrix} T_{1} \\ T_{2} \\ T_{3} \end{pmatrix} = \begin{pmatrix} 30 \\ 60 \\ 90 \end{pmatrix}.$$

Problem 5.

Write an augmented matrix corresponding to a system of two linear equations in three variables x_1 , x_2 , x_3 , whose solution set is the span of $\begin{pmatrix} -4 \\ 1 \\ 0 \end{pmatrix}$. Briefly justify your answer.

Solution.

This problem is familiar territory, except that here, we are asked to come up with a system with the prescribed span, rather than being handed a system and discovering the span.

Since the span of any vector includes the origin, the zero vector is a solution, so the system is homogeneous.

Note that the span of
$$\begin{pmatrix} -4\\1\\0 \end{pmatrix}$$
 is all vectors of the form $t \begin{pmatrix} -4\\1\\0 \end{pmatrix}$ where t is real.
It consists of all $\begin{pmatrix} x_1\\x_2\\x_3 \end{pmatrix}$ so that $x_1 = -4x_2$, $x_2 = x_2$, $x_3 = 0$.

The equation $x_1 = -4x_2$ gives $x_1 + 4x_2 = 0$, so one line in the matrix can be $\begin{pmatrix} 1 & 4 & 0 & | & 0 \end{pmatrix}$. The equation $x_3 = 0$ translates to $\begin{pmatrix} 0 & 0 & 1 & | & 0 \end{pmatrix}$. Note that this leaves x_2 free, as desired.

This gives us the augmented matrix

$$\left(\begin{array}{rrrr|r}
1 & 4 & 0 & 0 \\
0 & 0 & 1 & 0
\end{array}\right)$$

(Multiple examples are possible)

Let's check: the system has one free variable x_2 . The first line says $x_1 + 4x_2 = 0$, so $x_1 = -4x_2$. The second line says $x_3 = 0$. Therefore, the general solution is $x = \begin{pmatrix} -4x_2 \\ x_2 \\ 0 \end{pmatrix} = x_2 \begin{pmatrix} -4 \\ 1 \\ 0 \end{pmatrix}$ where x_2 is real. In other words, the solution set is the span of $\begin{pmatrix} -4 \\ 1 \\ 0 \end{pmatrix}$. The system of equations is

$$\begin{aligned} x_1 + 4x_2 &= 0\\ x_3 &= 0. \end{aligned}$$

[Scratch work]