

HAMILTONIAN ODE'S ON A SPACE OF DEFICIENT MEASURES *

L. CHAYES [†], W. GANGBO [‡], AND H. K. LEI [§]

Abstract. We continue the study (initiated in [1]) of Borel measures whose time evolution is provided by an interacting Hamiltonian structure. Here, the principal focus is the development and advancement of *deficiency* in the measure caused by displacement of mass to infinity in finite time. We introduce – and study in its own right – a regularization scheme based on a dissipative mechanism which naturally degrades mass according to distance traveled (in phase space). Our principal results are obtained based on some dynamical considerations in the form of a condition which forbids mass to return from infinity.

Key words. Infinite Dimensional Hamiltonian, ODEs on Measure Spaces, Wasserstein Metric.

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1. Introduction In this work, we further the study of time evolution for certain Borel measures whose underlying dynamic is provided by a *Hamiltonian* structure. In particular, for a given measure μ_t on $D := 2d$ -dimensional *phase space* for a fluid or particle system in d -dimensions, one is led to consider a “Hamiltonian functional”, $\mathcal{H}(\mu_t)$, whose gradient with respect to the Wasserstein metric (see Equation (2.19)) provides the velocity field which in turn evolves the measure. While the mass conserved case has already been considered in e.g., [1], our concern in this note is the problem of Hamiltonian dynamics where the kinematics allow for the possibility that particles may reach infinity in finite time. (As can be readily checked, dynamics subject to an external potential with a super-quadratic drop to negative infinity shall satisfy such a property).

Motivated by the fact that mass conserved dynamics can be described by an appropriate continuity equation, as described in [1], we begin by developing a weak theory of a *deficient* continuity equation where mass is degraded according to distance traveled in phase space. It is worth emphasizing that this is a natural regularization for which degradation of mass is everpresent; moreover, this regularization allows us to look at infinite volume measures from the outset. On the other hand, it is noted that while the work in [1] employs the Wasserstein distance – which is equivalent to vague convergence along with convergence of second moments, our result is much more modest: In the present note we shall content ourselves, ultimately, with distributional convergence, i.e., weak convergence restricted to finite volumes.

This restriction to finite volumes induces certain dynamical considerations. Indeed, it is almost a tautology that the dynamics cannot be well-described distributionally without some notion that particles cannot “return from infinity”. (Such a condition can be established in a variety of circumstances, the most trivial example being in the case of a radially symmetric potential, where the existence of infinitely many “outward” maxima clearly define regions of no return.) A general version of such a condition, which we refer to as a dynamical hypothesis, will be described in Section 3. With such a dynamical hypothesis in hand, we shall indeed be able to extract some limiting dynamics as our regularization parameter tends to zero and establish a mass convergence result as detailed in Section 4.

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[†]Department of Mathematics, UCLA, (lchayes@math.ucla.edu).

[‡]Department of Mathematics, Georgia Institute of Technology, (gangbo@math.gatech.edu).

[§]Department of Mathematics, California Institute of Technology, (thshelen@gmail.com).

2. Preliminaries

In this section we will introduce the deficient continuity equation and establish some basic properties.

2.1. Deficient Equation and a priori Estimates

DEFINITION 2.1. We will denote by \mathcal{M} the space of all finite Borel measures generated by the open sets in \mathbb{R}^D . Given some $\alpha \geq 0$ and a Borel measure $\mu \in \mathcal{M}$, we define

$$M_\alpha(\mu) = \mathbb{E}_\mu(e^{\alpha|X|})$$

to be the α -exponential moment of μ . We also let \mathcal{M}_α denote the set of all Borel measures with finite α -exponential moment.

Before we state a preliminary existence result for fixed velocity fields, we will make the following observation:

PROPOSITION 2.2. Let $T > 0$ and let $v: [0, T] \times \mathbb{R}^D \rightarrow \mathbb{R}^D$ be a Borel vector field such that $v_t := v(t, \cdot)$ is locally Lipschitz for every $t \in [0, T]$. Let us assume that for every compact $K \subset \mathbb{R}^D$, $f_K \in L^1(0, T)$, where

$$f_K(t) = \sup_{x \in K} |v_t| + \text{Lip}(v_t, K).$$

(i) Then for all x in \mathbb{R}^D , there exists a $\tau(x) > 0$ such that there exists a (unique) solution to the ODE

$$\dot{X}_t = v_t(X_t), \quad X_0 = x,$$

on $[0, \tau(x))$. Further, either $\tau(x) = T$ or $t \mapsto |X_t|$ is unbounded on $[0, \tau(x))$, in which case

$$\int_0^{\tau(x)} |\dot{X}_t| dt = \infty.$$

(ii) The function $\tau: \mathbb{R}^D \rightarrow (0, \infty)$ is lower semicontinuous and for $t \in (0, T)$ the function X_t is one-to-one on the open set

$$\mathbb{S}_t := \{x \in \mathbb{R}^D \mid \tau(x) > t\}.$$

Proof. For each x , existence up to some maximal time $\tau(x)$ follows by standard ODE theory given the assumption on v_t . Furthermore, the solution trajectories are continuous. If $\tau(x) < T$ and $t \mapsto |X_t|$ is bounded on $[0, \tau(x))$ then $t \mapsto X_t$ is Lipschitz on that set and so, it admits a left limit $X_{\tau(x)}$ at $\tau(x)$. Then the identity $X_t = X_0 + \int_0^t v_s \circ X_s ds$ can first be extended to $t = \tau(x)$ and then beyond. In particular, if $|X_{\tau(x)}|$ is bounded, then we could extend the solution of the ODE to a larger interval, contradicting the maximality of $\tau(x)$.

Let D_b denote the ball of radius b around the origin, and for $t < T$ set

$$\mathbb{B}_t(b) = \{x \in \mathbb{R}^D \mid \tau(x) > t, X(x, \cdot)[0, t] \subset D_b\}.$$

We shall next demonstrate that $\mathbb{B}_t(b)$ is an open set. Let $x \in \mathbb{B}_t(b)$ and y satisfying $|x - y| < \delta$ with δ to be specified momentarily: For $L > 0$ suppose that δ has been chosen so that

$$\delta < L e^{-\int_0^t f_{D_{b+L}}(s) ds}. \quad (2.1)$$

We claim that under these conditions, $y \in \mathbb{B}_t(b+L)$. Indeed, clearly $y \in \mathbb{B}_\vartheta(b+L)$ for $\vartheta > 0$ sufficiently small; let us suppose that ϑ is maximal and assume towards a contradiction that $\vartheta < t$. Letting $r(t) := |X_t(x) - X_t(y)|$ we directly see that for any $t' < \vartheta$,

$$\frac{dr}{dt}(t') \leq r(t') f_{D_{b+L}}(t').$$

Thus, certainly, by Gronwall's inequality $r(t') < L$ for any $t' \leq \vartheta$, but continuity then also implies that $r(\vartheta + \eta) < L$ for some sufficiently small $\eta > 0$, contradicting the maximality of ϑ . We conclude that $\vartheta \geq t$. So $y \in \mathbb{B}_t(b+L)$. Now, since $X(x, \cdot)[0, t]$ is compact we have that $x \in \mathbb{B}_t(b')$ for some $b' < b$; finally, choosing $L = b - b'$ we have $y \in \mathbb{B}_t(b)$ and we have established that $\mathbb{B}_t(b)$ is an open set.

As for the semicontinuity, let $x \in \mathbb{R}^D$ and choose an arbitrary positive number a smaller than $\tau(x)$ and then choose $t \in (\tau(x) - a, \tau(x))$. As $X(x, \cdot)[0, t]$ is a compact set, it is contained in a ball D_b . Choose $L = 1$, say, and δ – with δ as in Equation (2.1) (with $\delta \ll 1$). Since $D_\delta(x)$, the open ball of center x and radius δ , is contained in $\mathbb{B}_t(b+1)$ and we have $\tau \geq t > \tau(x) - a$ on $D_\delta(x)$. This proves that $\liminf_{y \rightarrow x} \tau(y) \geq \tau(x) - a$. As a is arbitrary we conclude that $\liminf_{y \rightarrow x} \tau(y) \geq \tau(x)$. Thus τ is lower semicontinuous and, moreover, it follows that \mathbb{S}_t an open set.

Finally, if $x, y \in \mathbb{S}_t$ are such that $X_t(x) = X_t(y)$ then the functions $s \rightarrow r_x(s) := X_{t-s}(x)$ and $s \rightarrow r_y(s) := X_{t-s}(y)$ satisfy

$$r_x(0) = r_y(0), \quad \dot{r}_x = w_s(r_x), \quad \dot{r}_y = w_s(r_y), \quad w_s := -v_{t-s}$$

on $[0, t]$. Hence, $r_x(t) = r_y(t)$ i.e. $x = y$, which proves that X_t is one-to-one on \mathbb{S}_t . \square

REMARK 2.3. Let v denote a velocity field satisfying the hypothesis of Proposition 2.2.

(i) To ensure that f_K is Borel measurable it suffices to assume that $v(\cdot, x)$ is Borel measurable for every $x \in \mathbb{R}^D$.

(ii) Let \mathcal{O} be the set of (x, t) such that $0 < t < \tau(x)$. The lower semicontinuity of τ ensures that \mathcal{O} is an open subset of $\mathbb{R}^D \times (0, \infty)$. Also, $(x, t) \rightarrow X_t(x)$ is continuous on \mathcal{O} .

PROPOSITION 2.4. For fixed $\alpha_0 > 0$, $\alpha > 0$, and $0 < T < \infty$, let $\mu_0 \in \mathcal{M}_{\alpha_0}$ denote some initial Borel measure on \mathbb{R}^D , and let v_t denote a velocity field satisfying the hypothesis of Proposition 2.2. Then

(i) there exists $(\mu_t)_{t \in [0, T]}$ such that

$$\partial_t \mu_t + \nabla \cdot (v_t \mu_t) = -\varepsilon |v_t| \mu_t, \quad (2.2)$$

in the sense of distribution: $\forall \varphi \in C_c^\infty(\mathbb{R}^D \times (0, T))$,

$$\int_0^T \int_{\mathbb{R}^D} (\partial_t \varphi + \langle v_t, \nabla \varphi \rangle) d\mu_t dt = \int_0^T \int_{\mathbb{R}^D} \varepsilon |v_t| \varphi d\mu_t dt;$$

(ii) the measure μ_t is supported by $X_t(\mathbb{S}_t)$ and

$$\int_{\mathbb{R}^D} \psi d\mu_t = \int_{\mathbb{S}_t} (R_t \psi) \circ X_t d\mu_0,$$

where R_t is defined as in Equation (2.4);

(iii) furthermore, if $\alpha \leq \min\{\alpha_0, \varepsilon\}$, $M_\alpha(\mu_t)$ is monotonically nonincreasing in t . In particular the total mass $M_0(\mu_t)$ is monotonically nonincreasing in t .

Proof. For b be a positive integer we select a map $\phi^b: \mathbb{R}^D \rightarrow D_{b+1}$ of class C^2 of Lipschitz constant less than or equal to b such that $\phi^b(x) = x$ for $|x| \leq b$, and $\phi^b(x) = 0$ for $|x| \geq 2+b$. Let X_t^b be the solution of the ODE as described in Proposition 2.2 when v is substituted by $v^b = v \circ \phi^b$. Note that as

$$|\dot{X}_t^b| \leq f_{D_{b+1}}, \quad f_{D_{b+1}} \in L^1(0, T),$$

X_t^b exists for all $t \in [0, T]$ and is invertible. Let $\mathbb{B}_t(b)$ be as above and observe that

$$x \in \mathbb{B}_t(b), \quad \implies \quad X_s^b(x) = X_s(x) \quad \forall \quad s \in [0, t]. \quad (2.3)$$

Indeed, for $x \in \mathbb{B}_t(b)$ and $s \leq t$

$$X_s(x) = x + \int_0^s v_\tau(X_\tau(x)) d\tau = x + \int_0^s v_\tau^b(X_\tau(x)) d\tau.$$

Set

$$\mu_t^{*,b} = X_t^b \# \mu_0, \quad \mu_t^b = R_t^b \mu_t^{*,b}$$

where R_t^b is defined on $[0, T] \times \mathbb{R}^D$ by

$$R_t^b \circ X_t^b = \exp\left(-\int_0^t \varepsilon |\dot{X}_s^b| d\tau\right).$$

Similarly, for $t < T$ and $x \in \mathbb{S}_t$ we define

$$R_t \circ X_t = \exp\left(-\int_0^t \varepsilon |\dot{X}_s| d\tau\right). \quad (2.4)$$

As

$$\partial_t \mu_t^b + \nabla \cdot (v_t^b R_t^b) = -\varepsilon |v_t^b| R_t^b \quad \text{and} \quad \partial_t \mu_t^{*,b} + \nabla \cdot (v_t^b \mu_t^{*,b}) = 0$$

in the sense of distribution on $(0, T) \times \mathbb{R}^D$,

$$\partial_t \mu_t^b + \nabla \cdot (v_t^b \mu_t^b) = -\varepsilon |v_t^b| \mu_t^b \quad (2.5)$$

in the sense of distribution on $(0, T) \times \mathbb{R}^D$. We use Equation (2.3) to observe for $t < T$

$$\lim_{b \rightarrow \infty} R_t^b \circ X_t^b(x) = \begin{cases} R_t \circ X_t(x) & \text{if } t < \tau(x), \\ 0 & \text{if } t \geq \tau(x) \end{cases}. \quad (2.6)$$

As $(t, x) \rightarrow R_t^b \circ X_t^b(x)$ is continuous the limiting function in Equation (2.6) is a Borel function. For $t \in [0, T)$ we define the measure μ_t supported by $X_t(\mathbb{S}_t)$ by

$$\int_{\mathbb{R}^D} \psi d\mu_t = \int_{\mathbb{S}_t} (R_t \psi) \circ X_t d\mu_0$$

for $\psi \in C_b(\mathbb{R}^D)$. By Equations (2.3) and (2.6)

$$\lim_{b \rightarrow \infty} \int_0^T \left(\int_{\mathbb{R}^D} \varphi(t, y) d\mu_t^b(y) \right) dt = \int_0^T \left(\int_{\mathbb{R}^D} \varphi(t, y) d\mu_t(y) \right) dt \quad (2.7)$$

for $\varphi \in C_b([0, T] \times \mathbb{R}^D)$.

1. Claim: $(\mu)_{t \in [0, T]}$ satisfies Equation (2.2).

Proof of claim 1. In light of Equation (2.5) it suffices to show for arbitrary $\varphi \in C_c^1((0, T) \times \mathbb{R}^D)$ that

$$\lim_{b \rightarrow \infty} \int_0^T \left(\int_{\mathbb{R}^D} \langle \nabla \varphi, v^b \rangle d\mu_t^b(y) \right) dt = \int_0^T \left(\int_{\mathbb{R}^D} \langle \nabla \varphi, v \rangle d\mu_t(y) \right) dt$$

and

$$\lim_{b \rightarrow \infty} \int_0^T \left(\int_{\mathbb{R}^D} \varphi |v^b| d\mu_t^b(y) \right) dt = \int_0^T \left(\int_{\mathbb{R}^D} \varphi |v| d\mu_t(y) \right) dt.$$

Let $r > 0$ be chosen so that – say – the set $[r, T-r] \times B_{1/r}$ contains the support of φ . Now let ω be such that $|v| < \omega$ on $[r, T-r] \times B_{1/r}$. Then once $b > \omega$, we have $\langle \nabla \varphi, v^b \rangle = \langle \nabla \varphi, v \rangle$ and so, Equation (2.7) yields the first identity of the claim. We obtain the second identity in a similar manner.

In the above, the left hand sides actually *equal* the right hand sides once b is large enough so that D_b subsumes the support of φ since then $v^b = v$ and we may apply Equation (2.7).

2. Claim: Let $\alpha \leq \min\{\alpha_0, \varepsilon\}$. Then $M_{\infty, \alpha}(\mu_t)$ is monotonically nonincreasing in t .

Proof of claim 2. Let $0 \leq t_1 < t_2 \leq T$. As v^b is of compact support Equation (2.5) implies

$$\frac{d}{dt} \int \psi d\mu_t^b = \int (\langle \nabla \psi, v_t^b \rangle - \varepsilon \psi |v_t^b|) d\mu_t. \quad (2.8)$$

so with $\psi = e^{\alpha|x|}$, we get

$$\frac{d}{dt} M_{\infty, \alpha}(\mu_t^b) = \int |v_t^b| e^{\alpha|y|} \left(\alpha \left\langle \frac{y}{|y|}, \frac{v_t^b}{|v_t^b|} \right\rangle - \varepsilon \right) d\mu_t \leq 0$$

holds if $\alpha \leq \varepsilon$, and hence,

$$M_{\infty, \alpha}(\mu_{t_2}^b) \leq M_{\infty, \alpha}(\mu_{t_1}^b). \quad (2.9)$$

As $\alpha \leq \varepsilon$ we have

$$R_t^b \circ X_t^b(x) \leq \exp -\alpha \left(\int_0^t |\dot{X}_s^b(x)| ds \right)$$

and so, the inequality

$$|X_t^b(x) - x| \leq \int_0^t |\dot{X}_s^b(x)| ds$$

yields

$$R_t^b \circ X_t^b(x) e^{\alpha|X_t^b(x)|} \leq e^{\alpha|x|}$$

Since $x \rightarrow \exp(\alpha|x|)$ belongs to $L^1(\mu_0)$, we may use Equations (2.3) and (2.6) and apply the Lebesgue dominated convergence theorem to obtain that

$$\lim_{b \rightarrow \infty} \int_{\mathbb{R}^D} R_t^b \circ X_t^b(x) e^{\alpha|X_t^b(x)|} d\mu_0(x) = \int_{\mathbb{S}_t} R_t \circ X_t(x) e^{\alpha|X_t(x)|} d\mu_0(x)$$

which shows that $M_{\infty,\alpha}(\mu_t^b)$ tends to $M_{\infty,\alpha}(\mu_t)$ as b tends to ∞ . This together with (2.9) proves the claim. \square

REMARK 2.5. *We make some remarks on some (almost) automatic extensions of these results.*

(i) *The fact that the α -exponential moment of the solution of (2.2) decreases in time ensures that we can repeat Proposition 2.4 on the interval $[T, 2T]$, \dots , $[nT, (n+1)T]$ to obtain that Equation (2.2) is satisfied on $[0, \infty) \times \mathbb{R}^D$.*

(ii) *If v is a velocity field satisfying the hypothesis of Proposition 2.2 and only the m^{th} moment of μ_0 is finite (i.e., μ_0 may not have an α -exponential moment) then the m^{th} moment of μ_t stays bounded on $[0, T]$. (In the particular case where $m=0$ the total mass of μ_t is less than or equal to that of μ_0 .) Indeed, let us define*

$$S_t(x) = \int_0^t |\dot{X}_\tau(x)| d\tau.$$

Then

$$\int_{\mathbb{R}^D} |y|^m d\mu_t(y) = \int_{S_t} e^{-\varepsilon S_t(x)} |X_t(x)|^m d\mu_0(x) \leq \int e^{-\varepsilon S_t(x)} (|x| + S_t(x))^m d\mu_0$$

Now we divide the integral into $\{x : S_t(x) < |x|\}$ and $\{x : S_t(x) > |x|\}$. The integral over the former region is bounded by 2^m times the initial moment, whereas the integral over the latter region is bounded by a constant depending on ε .

(iii) *Assume α , v and μ_0 are as in Proposition 2.4. Let $t \rightarrow \mu_t$ be the solution obtained in that proposition and let $\varphi \in C^1(\mathbb{R}^d)$. Then we claim, that after some computations along the lines of the proof of said Proposition, that*

$$\left| \int_{\mathbb{R}^D} \varphi d\mu_{t_2} - \int_{\mathbb{R}^D} \varphi d\mu_{t_1} \right| \leq (1+\varepsilon) \|\varphi\|_{C^1} \int_{t_1}^{t_2} \int_{\mathbb{R}^D} |v_s| d\mu_s ds. \quad (2.10)$$

Indeed, we can first obtain the inequality in Equation (2.10) for $\varphi \in C_c^1(\mathbb{R}^D)$. An approximation argument then yields the general case.

2.2. Limiting Measures and Equations

Let μ_t^ε denote a (distributional) solution to the deficient continuity equation

$$\partial_t \mu_t^\varepsilon + \nabla \cdot (\mu_t^\varepsilon v_t^\varepsilon) = -\varepsilon |v_t^\varepsilon| \mu_t^\varepsilon. \quad (2.11)$$

We will now establish existence of the necessary $\varepsilon \rightarrow 0$ limiting measures. We remark that here we will retrieve the limit abstractly, making no statement about the limiting dynamics. We will address *Hamiltonian* dynamics in the following section.

As before, we denote by X_t the characteristic in Equation (2.11): $\dot{X}_t = v_t(X_t)$, $X_0 = \text{Id}$.

REMARK 2.6. *We point out that in this section and the next, we will use the weakest form of convergence of measures: Distributional convergence, i.e., $\mu_n \rightharpoonup \mu$ if*

$$\forall \varphi \in C_c^\infty(\mathbb{R}^D), \quad \lim_{n \rightarrow \infty} \int \varphi d\mu_n = \int \varphi d\mu.$$

However, if $\{\int \psi d\mu_n\}_{n \in \mathbb{N}}$ is bounded for some nonnegative $\psi \in C(\mathbb{R}^D)$ such that $\psi(x)$ tends uniformly to ∞ as $|x|$ tends to ∞ (e.g., a moment condition) then distributional convergence is equivalent to narrow convergence which is defined as $\mu_n \xrightarrow{n} \mu$ if

$$\forall \varphi \in C_b(\mathbb{R}^D), \quad \lim_{n \rightarrow \infty} \int \varphi d\mu_n = \int \varphi d\mu.$$

So we will often (automatically) acquire narrow convergence but utilize C_c^∞ functions to carry out the relevant arguments.

We shall also use weak* convergence which is defined as $\mu_n \xrightarrow{*} \mu$ if

$$\forall \varphi \in C_0(\mathbb{R}^D), \quad \lim_{n \rightarrow \infty} \int \varphi d\mu_n = \int \varphi d\mu.$$

Since our measures are no longer probability measures, we prefer to not speak of tightness but instead think of them as Radon measures and abstractly extract a narrow limit point – which may very well have mass much less than the sequence from which it originated but is none the less a Radon measure. (Indeed, by the Riesz representation theorem, the dual of $C_0(\mathbb{R}^D)$ is isometrically isomorphic to the space of all Radon measures.) Then if we wish to establish some property of the limiting measure (e.g., that it satisfies some suitable equation) it is enough to work with functions in $C_c^\infty(\mathbb{R}^D)$, as was discussed in the previous paragraph.

Finally, as far as convergence of measures of sets are concerned, by standard properties of Radon measures it is the case that if $\mu_n \xrightarrow{*} \mu$ and A is a Borel set, then

$$\mu(A^\circ) \leq \liminf_n \mu_n(A) \leq \limsup_n \mu_n(A) \leq \mu(\bar{A}). \quad (2.12)$$

We refer the reader to e.g., [3], Chapter 1.9 for such results.

First let us extract a narrow continuity statement for measures satisfying the deficient continuity equation:

LEMMA 2.1. *Let v_t^ε be as in Proposition 2.2 and let $\varepsilon \in (0, 1)$. Suppose $(\mu_t^\varepsilon)_{t \in [0, T]}$ satisfies the deficient continuity Equation (2.11). Then $t \rightarrow \mu_t^\varepsilon$ is a continuous path in \mathcal{M} , when the latter space is endowed with the distributional convergence topology. Moreover, if the α^{th} moment of μ_0^ε is finite for some $\alpha > 0$ then $t \rightarrow \mu_t^\varepsilon$ is a continuous path in \mathcal{M} for the narrow convergence topology.*

Proof. Let $\varphi \in C_c^\infty(\mathbb{R}^D)$. By Equation (2.2) the distributional derivative of $t \rightarrow g_\varphi^\varepsilon(t) := \int \varphi d\mu_t^\varepsilon$ exists and is equal to

$$\int_{D \cap X_t^\varepsilon(\mathbb{S}_t)} (\langle \nabla \varphi, v_t^\varepsilon \rangle - \varepsilon |v_t^\varepsilon| \varphi) d\mu_t^\varepsilon$$

where D is an open ball containing the support of φ and \mathbb{S}_t is defined in Proposition 2.2, corresponding to v_t^ε . Let

$$k_D^\varepsilon(t) = \sup_{x \in D} |v_t^\varepsilon|. \quad (2.13)$$

We have

$$|\langle \nabla \varphi, v_t^\varepsilon \rangle - \varepsilon |v_t^\varepsilon| \varphi| \leq C k_D^\varepsilon(t)$$

for a constant C depending only on φ but independent of t . As $k_D^\varepsilon \in L^1(0, T)$ we conclude that $g_\varphi^\varepsilon \in W^{1,1}(0, T)$ and so, it is continuous.

Having established continuity in the distributional topology, continuity in the narrow topology is readily established under the stated conditions by standard approximation arguments. Indeed, for $\varphi \in C_b^\infty$ we may write $\varphi = \varphi_n + \varphi - \varphi_n$ with $\varphi_n \in C_c^\infty$ satisfying $\varphi_n \leq \varphi$ and $\varphi - \varphi_n$ supported only outside a large region (tending to all of \mathbb{R}^D as $n \rightarrow \infty$). Remark 2.5 ensures if the m^{th} moment of μ_0^ε is finite for some $m > 0$

then the m^{th} moment of μ_t^ε remains uniformly bounded on $[0, T]$. This provides us with a uniform tightness condition that can be used to estimate the “non-compact” portion of φ . \square

REMARK 2.7. *Further suppose in Lemma 2.1 that, e.g., $|\mu_t^\varepsilon| \leq 1$ and that for any compact set $K \subset \mathbb{R}^D$, there exists some constant $C(K) > 0$ such that for all ε ,*

$$\sup_{t \in [0, T], x \in K} |v_t^\varepsilon(x)| \leq C(K). \quad (2.14)$$

That is, the velocity fields are locally bounded, uniformly for all ε and t of interest.

Let us record that in the proof of that Lemma we have exhibited a functional $\varphi \rightarrow C_\varphi$ of $C_c^\infty(\mathbb{R}^D)$ into $(0, \infty)$ such that if D is an open ball containing the support of φ then

$$\|g_\varphi^\varepsilon\|_{W^{1,1}(0, T)} \leq C_\varphi \int_0^T k_D(t) dt, \quad g_\varphi^\varepsilon(t) := \int \varphi d\mu_t^\varepsilon.$$

But since $k_D \in L^\infty(0, T)$, we have in fact that $g_\varphi^\varepsilon \in W^{1, \infty}(0, T)$ for all ε and hence it is Lipschitz, with Lipschitz constant $\|k_D\|_{L^\infty}$. Thus, it is emphasized, that if the velocity field is bounded uniformly in ε , so is the resulting estimate on the relevant time derivative.

PROPOSITION 2.8. *Suppose $\sup_\varepsilon |\mu_0^\varepsilon| < \infty$ and we have v_t^ε and μ_t^ε such that Equations (2.11) and (2.14) hold. Then there exists a sequence (ε_n) decreasing to 0 such that $(\mu_t^{\varepsilon_n})$ has a distributional limits μ_t as n tends to ∞ , for all $t \in [0, T]$. Furthermore, $t \rightarrow \mu_t$ is continuous for the distributional convergence.*

Proof. Assume for instance that $|\mu_0^\varepsilon| \leq 1$. Remark 2.5 ensures that $|\mu_t^\varepsilon| \leq 1$ uniformly in t and ε . Using a diagonal sequence argument we can apply the Banach–Alaoglu theorem to obtain $(\varepsilon_n) \subset (0, \infty)$ converging to 0 as n tends to ∞ such that $(\mu_t^{\varepsilon_n})$ converges in the distributional sense to some $\mu_t \in \mathcal{M}$ for e.g., each $t \in \mathcal{D} := (0, T) \cap \mathbb{Q}$.

1. Claim: If $t \in (0, T)$ then for any sequence $(t_k) \subset \mathcal{D}$ converging to t we have that $\mu_{t_k} \rightarrow \mu_t$ for some $\mu_t \in \mathcal{M}$ independently of the sequence (t_k) . (That is, the limit can be extended to all $t \in [0, T]$.)

Proof of claim. By the Banach–Alaoglu theorem the set $(\mu_t)_{t \in \mathcal{D}}$ is pre-compact for the distributional topology. Let $(t_k), (t_k^*) \subset \mathcal{D}$ be sequences converging to t as k tends to ∞ and suppose that $\mu_{t_k} \rightarrow \nu$ and $\mu_{t_k^*} \rightarrow \nu^*$ as k tends to ∞ . Let D be an open ball of radius r containing the support of an arbitrarily fixed function $\varphi \in C_c^\infty(\mathbb{R}^D)$, set $f_D(t) = C(D)$ and as in Remark 2.7 set

$$g_\varphi^\varepsilon(t) := \int \varphi d\mu_t^\varepsilon, \quad g_\varphi(t) := \int \varphi d\mu_t.$$

Let C_φ be as in Remark 2.7, then since the estimates are uniform in ε we may let $\varepsilon_n \rightarrow 0$ in that Remark to obtain

$$|g_\varphi(t_k) - g_\varphi(t_k^*)| \lesssim C_\varphi |t_k - t_k^*| \cdot C(D). \quad (2.15)$$

Letting k tend to ∞ we obtain

$$\int_{\mathbb{R}^D} \varphi d\nu = \int_{\mathbb{R}^D} \varphi d\nu^*.$$

As $\varphi \in C_c^\infty(\mathbb{R}^D)$ is arbitrary we conclude that $\nu = \nu^*$ which proves the claim.

2. Claim: If $t \in (0, T)$ then $(\mu_t^{\varepsilon_n})$ converges in the distributional sense to $\mu_t \in \mathcal{M}$.

Proof of claim. We use Equation (2.15) and the way $t \rightarrow \mu_t$ has been extended to $(0, T)$ to obtain for $t, t^* \in (0, T)$

$$|g_\varphi(t) - g_\varphi(t^*)| \lesssim \bar{C}|t - t^*| \quad \forall t, t^* \in (0, T), \quad \bar{C} := C_\varphi \cdot C(D). \quad (2.16)$$

Fix $t \in (0, T)$. Then for $t_k \in \mathcal{D}$ we have

$$\begin{aligned} |g_\varphi^{\varepsilon_n}(t) - g_\varphi(t)| &\leq |g_\varphi^{\varepsilon_n}(t) - g_\varphi^{\varepsilon_n}(t_k)| + |g_\varphi^{\varepsilon_n}(t_k) - g_\varphi(t_k)| + |g_\varphi(t_k) - g_\varphi(t)| \\ &\lesssim \bar{C}|t - t_k| + |g_\varphi^{\varepsilon_n}(t_k) - g_\varphi(t_k)|. \end{aligned}$$

Fixing k and passing to the limit when n tends to infinity we conclude that

$$\limsup_{n \rightarrow \infty} |g_\varphi^{\varepsilon_n}(t) - g_\varphi(t)| \lesssim \bar{C}|t - t_k|.$$

We then let t_k tend to t to conclude that

$$\lim_{n \rightarrow \infty} g_\varphi^{\varepsilon_n}(t) = g_\varphi(t)$$

which proves the claim. \square

REMARK 2.9. *We remark that it is in fact also possible to abstractly retrieve some limiting velocity fields $(v_t)_{t \in [0, T]}$ so that together with the limiting measures $(\mu_t)_{t \in [0, T]}$ the continuity equation*

$$\partial_t \mu_t + \nabla \cdot (\mu_t v_t) = 0 \quad (2.17)$$

is satisfied. Indeed, the basis for such a result is Lemma 7.2 in [1], which can be adapted to deficient measures mutatis mutandis. In our case we also have the additional complication that the velocity fields have only a local bound. However, this can be dispensed with by inserting another diagonalization procedure where we consider finite volume measures, $\mu_t^{\varepsilon, L}$, which are supported in regions of scale L . Then we may first take ε to zero, and then L to infinity. For the principal results of this note, this route will be avoided due (in part) to the fact that the velocity field and its limit must (and will) be produced on the basis of an explicit dynamical structure.

2.3. Hamiltonian Dynamics With Mass Dissipation

DEFINITION 2.10. *Given μ a measure on \mathbb{R}^D where $D = 2d$ – and where we denote $x = (p, q)$ – we define our Hamiltonian to be*

$$\mathcal{H}(\mu) = \frac{1}{2} \int |p|^2 d\mu(x) + \frac{1}{2} \int (W * \mu)(q) d\mu(x) + \int \Phi(q) d\mu(x), \quad (2.18)$$

where W and Φ are both functions of q and W is even. We further assume that:

- $W \in C_c^2(\mathbb{R}^d)$.
- $\Phi \in C^2(\mathbb{R}^d)$.

We let a denote the range of the interaction – i.e., W is supported on a ball of radius a . Although not always strictly necessary, we shall further assume, with no essential loss of generality, that Φ is polynomially bounded:

$$|\Phi(q)| \leq B_1 |q|^{b_2}$$

for finite constants B_1 and b_2 .

Formally, the gradient of \mathcal{H} with respect to the 2-Wasserstein metric at μ is the functional

$$(p, q) \rightarrow \nabla_W \mathcal{H}(\mu)(p, q) = [p, \nabla(W * \mu + \Phi)(q)] =: V_\mu(p, q) \quad (2.19)$$

provided that μ is sufficiently well-behaved (cfr., e.g., [2] or [4]). We shall use Equation (2.19) in order to define the relevant dynamics.

Let J be the $D \times D$ symplectic matrix so that $J(p, q) = (-q, p)$. We say that $(\mu_t^\varepsilon)_{t \in [0, T]}$ solves the deficient Hamiltonian ODE with initial condition μ_0 if it satisfies

$$\partial_t \mu_t^\varepsilon + \nabla \cdot (J \nabla_W \mathcal{H}(\mu_t^\varepsilon) \mu_t^\varepsilon) = -\varepsilon |J \nabla_W \mathcal{H}(\mu_t^\varepsilon)| \mu_t^\varepsilon. \quad (2.20)$$

Similarly, we say that $(\mu_t)_{t \in [0, T]}$ solves the Hamiltonian ODE with initial condition μ_0 if it satisfies

$$\partial_t \mu_t + \nabla \cdot (J \nabla_W \mathcal{H}(\mu_t) \mu_t) = 0. \quad (2.21)$$

Equations (2.20) and (2.21) are again understood in the appropriate distributional sense, by testing against functions $\varphi \in C_c^\infty((0, T) \times \mathbb{R}^D)$.

To enable us to extract limiting Hamiltonian dynamics, let us now prove:

LEMMA 2.2. Set $V_\mu = J \nabla_W \mathcal{H}(\mu)$ and suppose

- (μ_n) is of uniformly bounded total mass and converges to μ in the distributional sense.
- We have the tightness in p condition: $\lim_{r \rightarrow \infty} C_r(\bar{q}) = 0$ for all \bar{q} where

$$C_r(\bar{q}) = \sup_{n \in \mathbb{N}} \int_{B_r^c \times \mathbb{R}^d} |\nabla W|(\bar{q} - q) d\mu^n(p, q).$$

Then (V_{μ_n}) converges uniformly to V_μ on compact sets. So, in particular,

$$V_{\mu_n} \mu_n \rightharpoonup V_\mu \mu \quad \text{and} \quad |V_{\mu_n}| \mu_n \rightharpoonup |V_\mu| \mu$$

in the sense of distribution.

Proof. It suffices to show that $(\nabla W * \mu_n)$ converges uniformly to $\nabla W * \mu$ on compact sets. As (μ_n) is of uniformly bounded total mass, $(\nabla W * \mu_n)$ is a bounded subset of $W^{1, \infty}(\mathbb{R}^d)$ and so, by the Ascoli-Arzelà theorem $(\nabla W * \mu_n)$ is precompact in $C(B_Q)$ – where B_Q is a ball of radius Q in \mathbb{R}^d – for any $Q > 0$. To show that $(\nabla W * \mu_n)$ converges uniformly to $\nabla W * \mu$ on B_Q it suffices to show that it converges pointwise to $\nabla W * \mu$.

For $r > 0$ let $\theta_r \in C(\mathbb{R})$ be a monotone nondecreasing continuous function such that $0 \leq \theta_r \leq 1$,

$$\begin{cases} \theta_r(p) = 1 & \text{for } |p| \geq r \\ \theta_r(p) = 0 & \text{for } |p| \leq r - 1. \end{cases}$$

Using for μ_n the decomposition

$$\nabla W * \mu_n(\bar{q}) = \int_{\mathbb{R}^D} \nabla W(\bar{q} - q)(1 - \theta_r(|p|)) d\mu_n(p, q) + \int_{\mathbb{R}^D} \nabla W(\bar{q} - q)\theta_r(|p|) d\mu_n(p, q)$$

and writing a similar decomposition for μ we obtain

$$\begin{aligned} & |\nabla W * \mu_n(\bar{q}) - \nabla W * \mu(\bar{q})| \\ & \leq \left| \int_{\mathbb{R}^D} \nabla W(\bar{q} - q)(1 - \theta_r(|p|))(d\mu_n(p, q) - d\mu(p, q)) \right| + 2C_{r-1}(\bar{q}) \end{aligned} \quad (2.22)$$

To obtain the upper bound in Equation (2.22) we have used distributional convergence:

$$\int_{\mathbb{R}^D} |\nabla W(\bar{q}-q)|\theta_r(|p|) d\mu(p,q) \leq \limsup_{n \rightarrow \infty} \int_{\mathbb{R}^D} |\nabla W(\bar{q}-q)|\theta_r(|p|) d\mu_n(p,q) \leq C_{r-1}(\bar{q}).$$

Finally, we use that $(p,q) \rightarrow \nabla W(\bar{q}-q)(1-\theta_r(|p|))$ is of compact support and again utilize the fact that (μ_n) converges to μ in the distributional sense to conclude from Equation (2.22) that

$$\limsup_{n \rightarrow \infty} |\nabla W * \mu_n(\bar{q}) - \nabla W * \mu(\bar{q})| \leq 2C_{r-1}(\bar{q}).$$

Letting r tend to ∞ we have that $(\nabla W * \mu_n(\bar{q}))$ converges pointwise to $\nabla W * \mu(\bar{q})$. \square

THEOREM 2.11 (Existence of Solution to Deficient Hamiltonian ODE). *For fixed $\alpha_0 > 0$, $\varepsilon > 0$, and $0 < T < \infty$, let $\mu_0 \in \mathcal{M}_{\alpha_0}$ denote some initial Borel measure on \mathbb{R}^D and let \mathcal{H} be the Hamiltonian in Definition 2.10. Assume for simplicity that the total mass of μ_0 is 1. Then there exists a path $t \rightarrow \mu_t^\varepsilon \in \mathcal{M}_\alpha$ where $\alpha < \min\{\alpha_0, \varepsilon\}$ such that*

(i) $(\mu_t^\varepsilon)_{t \in [0, T]}$ satisfies the deficient Hamiltonian ODE

$$\partial_t \mu_t^\varepsilon + \nabla \cdot (J \nabla_W \mathcal{H}(\mu_t^\varepsilon) \mu_t^\varepsilon) = -\varepsilon |J \nabla_W \mathcal{H}(\mu_t^\varepsilon)| \mu_t^\varepsilon. \quad (2.23)$$

(ii) $t \rightarrow \mu_t^\varepsilon \in \mathcal{M}_\alpha$ is narrowly continuous and $M_\alpha(\mu_t^\varepsilon)$ is monotonically nonincreasing in t . In particular, $M_0(\mu_t^\varepsilon) \leq 1$ for $t \in [0, T]$.

Proof. The construction of μ_t^ε uses roughly the discretization scheme of §6 of [1], which goes as follows:

1. For $n \geq 1$ define the step size $h = T/n$.
2. We start with $\mu_0^{\varepsilon, n} = \mu_0$ and define $v_0^{\varepsilon, n} = J \nabla_W \mathcal{H}(\mu_0^{\varepsilon, n})$.
3. For $t \in [kh, (k+1)h)$ we define $\mu_t^{\varepsilon, n}$ to be the solution to the deficient equation given in Proposition 2.4 with the constant velocity field

$$v_{kh}^{\varepsilon, n} = J \nabla_W \mathcal{H}(\mu_{kh}^{\varepsilon, n}).$$

By construction, we therefore see that $(\mu_t^{\varepsilon, n})_{t \in [0, T]}$ satisfies

$$\partial_t \mu_t^{\varepsilon, n} + \nabla \cdot \left(\mu_t^{\varepsilon, n} J \nabla_W \mathcal{H}(\mu_{[t/h]h}^{\varepsilon, n}) \right) = -\varepsilon \left| J \nabla_W \mathcal{H}(\mu_{[t/h]h}^{\varepsilon, n}) \right| \mu_t^{\varepsilon, n}. \quad (2.24)$$

Furthermore, Proposition 2.4 allows us to write

$$\int_{\mathbb{R}^D} \varphi d\mu_t^{\varepsilon, n} = \int_{\mathbb{S}_t^{\varepsilon, n}} (R_t^{\varepsilon, n} \varphi) \circ X_t^{\varepsilon, n} d\mu_0 \quad (2.25)$$

for all $\varphi \in C_c^\infty(\mathbb{R}^D)$. Here $X^{\varepsilon, n}$ is the flow defined by

$$\dot{X}_t^{\varepsilon, n} = v_t^{\varepsilon, n}(X_t^{\varepsilon, n}), \quad X_0^{\varepsilon, n} = x$$

and

$$R_t^{\varepsilon, n} \circ X_t^{\varepsilon, n} = \exp\left(-\int_0^t \varepsilon |v_s^{\varepsilon, n}(X_s^{\varepsilon, n})| ds\right).$$

By Proposition 2.4, (iii) $t \rightarrow M_\alpha(\mu_t^{\varepsilon, n})$ is monotone nonincreasing. In particular, the total masses of the μ_t^{ε, n_k} 's are uniformly bounded. Proceeding as in (the proof of)

Proposition 2.8 we obtain the existence of an increasing sequence of natural numbers $(n_k)_{k \in \mathbb{N}}$ such that as k tends to ∞ , $(\mu_t^{\varepsilon, n_k})_{k \in \mathbb{N}}$ converges in the sense of distribution to a measure μ_t^ε for each $t \in [0, T]$. In order to avoid adding a new subscript we shall write that $(\mu_t^{\varepsilon, n})_{n \in \mathbb{N}}$ converges in the sense of distribution to a measure μ_t^ε for each $t \in [0, T]$ where n is restricted to an appropriate subset of \mathbb{N} . Observing that by disintegration and Markov's inequality that for all $r > 0$ and $\bar{q} \in \mathbb{R}^d$ we have

$$\begin{aligned} \int_{B_r^c \times \mathbb{R}^d} |\nabla W(\bar{q} - q)| d\mu_t^{\varepsilon, n}(p, q) &\leq e^{-\alpha r} \int e^{\alpha|(p, q)|} |\nabla W(\bar{q} - q)| d\mu_t^{\varepsilon, n}(p, q) \\ &\leq e^{-\alpha r} M_\alpha(\mu_0) \|W\|_{C^2}, \end{aligned} \quad (2.26)$$

we can employ Lemma 2.2 to obtain for fixed $t \in [0, T]$

$$\mu_t^{\varepsilon, n} \nabla_W \mathcal{H}(\mu_t^{\varepsilon, n}) \quad \text{converges in the distributional sense to} \quad \mu_t^\varepsilon \nabla_W \mathcal{H}(\mu_t^\varepsilon) \quad (2.27)$$

and

$$\mu_t^{\varepsilon, n} |\nabla_W \mathcal{H}(\mu_t^{\varepsilon, n})| \quad \text{converges in the distributional sense to} \quad \mu_t^\varepsilon |\nabla_W \mathcal{H}(\mu_t^\varepsilon)|. \quad (2.28)$$

By Remark 2.5, (iii) there exists a constant \bar{m} independent of $t \in [0, T]$ and $k \in \mathbb{N}$ such that

$$|\nabla_W \mathcal{H}(\mu_{[t/h]h}^{\varepsilon, n}) - \nabla_W \mathcal{H}(\mu_t^{\varepsilon, n})| = |\nabla W * \mu_{[t/h]h}^{\varepsilon, n} - \nabla W * \mu_t^{\varepsilon, n}| \leq h\bar{m}.$$

This, together with Equations (2.27), (2.28) and the fact that the total masses of $\{\mu_t^{\varepsilon, n}\}_{t, n}$ are bounded uniformly in t and n imply that

$$\mu_t^{\varepsilon, n} \nabla_W \mathcal{H}(\mu_{[t/h]h}^{\varepsilon, n}) \quad \text{converges in the distributional sense to} \quad \mu_t^\varepsilon \nabla_W \mathcal{H}(\mu_t^\varepsilon) \quad (2.29)$$

and

$$\mu_t^{\varepsilon, n} |\nabla_W \mathcal{H}(\mu_{[t/h]h}^{\varepsilon, n})| \quad \text{converges in the distributional sense to} \quad \mu_t^\varepsilon |\nabla_W \mathcal{H}(\mu_t^\varepsilon)|. \quad (2.30)$$

We combine Equations (2.24), (2.29) and (2.30) and use the fact that $(\nabla_W \mathcal{H}(\mu_t^{\varepsilon, n}))$ is bounded uniformly in t, n on compact sets to conclude that $(\mu_t^\varepsilon)_{t \in [0, T]}$ satisfies Equation (2.23). Thus reasoning as in the proof of Proposition 2.4, $t \rightarrow M_\alpha(\mu_t^\varepsilon)$ is monotone nonincreasing. The narrow continuity claim of item (ii) now immediately follows from Lemma 2.1. \square

REMARK 2.12. *We note that while in order to obtain existence of dynamics with non-zero ε an a priori estimate as in Equation (2.26) already suffices, more is required to obtain some control which is uniform in ε to retrieve limiting ($\varepsilon=0$) dynamics. Here is where the dynamical considerations will come into play (in particular, see Lemma 4.1).*

3. Dynamical Hypothesis

Here we will let (p, q) =(position, momentum) denote canonical variables and p_t, q_t denote the associated Lagrangian trajectories (or characteristics) with dynamics dictated by the relevant Hamiltonian. Indeed, we shall have occasion to consider single particle Hamiltonian dynamics with some Hamiltonian H (the Hamiltonian \mathcal{H} as defined in Definition 2.10 is the integrated total Hamiltonian of the whole system). We recall the canonical equations of Hamiltonian dynamics:

$$\dot{p} = -\frac{\partial H}{\partial q}, \quad \dot{q} = \frac{\partial H}{\partial p}. \quad (3.1)$$

We will assume that the Hamiltonian is given by

$$H(p, q, t) = \frac{1}{2}|p|^2 + \Phi(q) + \Psi(t, q).$$

Here, $\Phi, \Psi(\cdot, t) \in C^2(\mathbb{R}^d)$, Ψ is a Borel function defined on $[0, \infty) \times \mathbb{R}^d$ and there exists $B > 0$ such that

$$|\nabla \Psi(t, q)| < B \quad \forall t \geq 0, q \in \mathbb{R}^d. \quad (3.2)$$

Let $u \in C^2(\mathbb{R})$ be such that

$$u'(r) \geq B + \max_{|q|=r} \langle \nabla \Phi(q), \hat{q} \rangle, \quad r \geq 0, \quad (3.3)$$

where $\hat{q}|q|=q$. We consider the auxiliary ‘‘Hamiltonian’’

$$\tilde{H}(p, q) = \frac{1}{2} \langle p, \hat{q} \rangle^2 + \Upsilon(q) \quad \text{where} \quad \Upsilon(q) = u(|q|).$$

LEMMA 3.1 (Single Particle Dynamics). *Consider single particle Hamiltonian dynamics Equation (3.1). We define a \star -ring by the condition that*

$$\Upsilon(q) < \Upsilon(q^*), \quad \text{for all } |q| > |q^*| \quad (3.4)$$

and assume that $q^* \neq 0$. Fix $\bar{t} \in [0, T]$. Then for all characteristics which start out inside the region bounded by the \star -ring, in the sense that $|q_0| < |q^*|$, either

$$|q_t| \leq |q^*|, \quad \text{for all } t \geq \bar{t},$$

or

$$|q_t| \rightarrow \infty$$

with nonvanishing radial speed, i.e., there exists some $t_* > \bar{t}$ such that $|q_{t_*}| = |q^*|$ and

$$\frac{d|q_t|}{dt}(t) \geq \frac{d|q_t|}{dt}(t_*) > 0, \quad \text{for all } t \geq t_*.$$

Proof. We first claim that, provided $\frac{d|q|}{dt} > 0$ on an interval, the quantity \tilde{H} is increasing on that interval. Using Equations (3.2) and (3.3), direct computations give

$$\frac{d^2|q|}{dt^2} = \frac{\langle \ddot{q}, q \rangle}{|q|} + \frac{|\dot{q}|^2|q|^2 - \langle \dot{q}, q \rangle^2}{|q|^3} \geq \frac{\langle \ddot{q}, q \rangle}{|q|} = -\langle \nabla \Phi(q) + \nabla \Psi(t, q), \hat{q} \rangle > -\langle \nabla \Upsilon(q), \hat{q} \rangle \quad (3.5)$$

where the last inequality is strict due to (the strict inequality in) Equation (3.2).

As Υ depends only on $|q|$,

$$\langle \nabla \Upsilon(q), \hat{q} \rangle = \langle \nabla \Upsilon(q), \hat{q} \rangle \frac{d|q_t|}{dt} \quad (3.6)$$

and so, by Equation (3.5)

$$\frac{d\tilde{H}}{dt} = \frac{d|q|}{dt} \frac{d^2|q|}{dt^2} + \langle \nabla \Upsilon(q), \hat{q} \rangle \frac{d|q|}{dt} = \frac{d|q|}{dt} \left(\frac{d^2|q|}{dt^2} + \langle \nabla \Upsilon(q), \hat{q} \rangle \right) > 0.$$

Suppose now that it is not the case that $|q_t| \leq |q^*|$ for all $t \geq \bar{t}$. Set

$$t_* = \inf\{t : |q(t)| > |q^*|, t \geq \bar{t}\}.$$

1. Claim: We have

$$|q(t_*)| = |q^*| \quad \text{and} \quad \frac{d|q|}{dt}(t_*) > 0$$

Proof of claim. What is obvious is that $|q(t_*)| = |q^*|$ and the derivative of $|q|$ at t_* is nonnegative. Assume on the contrary that the derivative vanishes. Then we necessarily have (by e.g., simple expansion) that the second derivative of $|q|$ at t_* is nonpositive and so since Equation (3.5) reads

$$\frac{d^2|q|}{dt^2}(t_*) > -u'(|q^*|) \tag{3.7}$$

whereas Equation (3.4) yields $u'(|q^*|) \leq 0$ we have a contradiction.

2. Claim: $\frac{d|q|}{dt}(t) \geq \frac{d|q|}{dt}(t_*)$ for all $t \geq t_*$.

Proof of claim. Assume on the contrary that

$$E = \left\{ t \geq t_* : \frac{d|q|}{dt}(t) < \frac{d|q|}{dt}(t_*) \right\} \neq \emptyset.$$

Let t_1 be the infimum of E . First it is noted that $t_1 > t_*$ since $\frac{d^2|q|}{dt^2}(t_*) > 0$ by Equation (3.7). But then

$$\frac{d|q|}{dt}(t_1) = \frac{d|q|}{dt}(t_*) < \frac{d|q|}{dt}(t) \quad \forall t \in (t_*, t_1)$$

and so, $|q(t_1)| > |q^*|$. Thus,

$$\tilde{H}(p(t_1), q(t_1)) < \tilde{H}(p(t_*), q(t_*))$$

which is a contradiction, since \tilde{H} is *increasing* on the interval $[t_*, t_1]$. \square

REMARK 3.1. *Note that in the proof of Lemma 3.1 we have proven, in the last claim, the following general result. If $t_* \in [0, T)$ satisfies*

$$|q(t_*)| = |q^*| > 0 \quad \text{and} \quad \frac{d|q|}{dt}(t_*) > 0$$

then $\frac{d|q|}{dt}(t) \geq \frac{d|q|}{dt}(t_)$ for all $t \geq t_*$. In particular \tilde{H} is increasing on the interval $[t_*, T]$.*

We make final assumptions on u' which will allow us to summarize our observations in this section in the following dynamical hypothesis to which we shall refer later:

HYPOTHESIS 3.2. *We postulate existence of $\Upsilon(q) = u(|q|)$ where $u \in C^2(\mathbb{R})$ satisfies Equation (3.3). We assume that there is a sequence $\{q_L^*\}_{L=1}^\infty$ such that $|q_L^*|$ increases to ∞ and for all q_L^* ,*

$$\Upsilon(q) < \Upsilon(q_L^*) \quad \text{for all} \quad |q| > |q_L^*|. \tag{3.8}$$

As a matter of notation we will sometimes denote generic elements of the sequence by L^ or just L when the context is clear.*

Let us also define the phase space cylinders

$$\Omega_{L^*} = \mathbb{R}^d \times B_{L^*},$$

where B_L denotes the ball in \mathbb{R}^d of radius L centered at the origin, and refer to them as spatial regions of no return.

REMARK 3.3. We note that the existence of unbounded (in q) spatial regions of no return is certainly guaranteed by the condition that $\Upsilon(q)$ decreases in $|q|$. Moreover, if additionally $\Upsilon(q) \sim -|q|^{1+R}$ with $R > 1$, then, inevitably, the unbounded motion will reach infinity in finite time.

REMARK 3.4. We emphasize that since the dynamical hypothesis is some uniform in ε control on the dynamics, the no return condition is inherited in any $\varepsilon \rightarrow 0$ limit.

4. Consequences of Dynamical Hypothesis

4.1. Limiting Hamiltonian ODE

As a first consequence of the dynamical hypothesis we will retrieve some limiting dynamics (meaning the relevant equation of continuity driven by the appropriate velocity field). In light of the content of Lemma 2.2, we see that we are first to estimate, for fixed t , the quantity

$$\tilde{C}_r(\mu_t^\varepsilon, \bar{q}) := \int_{\mathbb{R}^D} \theta_r(p) |\nabla W(\bar{q} - q)| d\mu_t^\varepsilon(p, q),$$

(in the ensuing we will omit the tilde as it should cause no confusion) where μ_t^ε 's are given by Theorem 2.11 and θ_r is supported outside the ball of radius r (Lemma 4.1). Further, we will have to produce some control on the time evolution of the relevant velocity fields, which is now not “automatic” since ε is tending to zero (Lemma 4.2).

Since the up and coming argument requires pulling trajectories back to μ_0 , we shall work directly with the time discretized measures which, by construction, satisfy the pushforward equation $\mu_t^{\varepsilon, n} = X_t^{\varepsilon, n} \# \mu_0$ (see Proposition 2.4 as it applies in the proof of Theorem 2.11).

We have the following tightness estimate:

LEMMA 4.1. *Let $T > 0$ and let $(\mu_t^{\varepsilon, n})_{t \in [0, T]}$ be the time discretized measures as constructed in the proof of Theorem 2.11. Suppose further that*

- *W is supported on the ball of radius a around the origin and there is some $B \geq 0$ such that*

$$|W| \leq B \quad \text{and} \quad |\nabla W| < B;$$

- *There is a “bounding” potential Υ , which is uniform in ε, n , corresponding to Φ and $\Psi^n := W * \mu_t^{\varepsilon, n}$ (see Equation (3.3) and the display which follows) satisfying the condition in Hypothesis 3.2.*

Let $Q > 0$ and let $C_r(\mu_t^{\varepsilon, n}, \bar{q})$ be defined as in Lemma 2.2, then for L as in Hypothesis 3.2 sufficiently large so that (cfr., Definition 2.10 for the meaning of a)

$$|q_L^*| > Q + a,$$

we have

$$\forall \bar{q} \in B_Q(0), \quad \forall t \in [0, T], \quad \forall \varepsilon > 0, \quad \forall n$$

the bound

$$C_r(\mu_t^{\varepsilon,n}, \bar{q}) \leq B(\mu_0(Q_L^*) + \mu_0(B_{r^*}^c \times \mathbb{R}^d)).$$

Here Q_L^* denotes the complement of the cylinder $\Omega_L^* := \mathbb{R}^d \times B_{|q_L^*|}$ and r is sufficiently large so that (at least)

$$r^* = r - 1 - M_L T > 0,$$

where

$$M_L = B + \sup_{q \in B_{|q_L^*|}} |\nabla \Phi(q)|.$$

Proof. We have that

$$\begin{aligned} C_r(\mu_t^{\varepsilon,n}, \bar{q}) &= \int |\nabla W(\bar{q} - q_t)| \theta_r(p_t) d\mu_t^{\varepsilon,n} \\ &= \int \theta_r(p_t) |\nabla W(\bar{q} - q_t)| R_t^{\varepsilon,n}(p_t, q_t) d\mu_0(p, q); \end{aligned}$$

here it is re-emphasized that the validity of the pull back to μ_0 has been assured by the manner in which the measures $\mu_t^{\varepsilon,n}$ have been constructed. By invoking the dynamical condition, for trajectories starting inside Ω_L^* this quantity can be bounded depending on whether the position marginal of the trajectory has ever left $B_{|q_L^*|}$ by time t : If the trajectory never left, then the acceleration can be bounded by M_L whereas if the trajectory leaves, then it is guaranteed not to return by Lemma 3.1 and so since $|q_L^*|$ is outside the interaction range of any point in B_Q , $\nabla W(\bar{q} - q_t) = 0$.

More precisely, let us partition the space of all possible *initial* conditions in phase space into three sets:

$$\begin{aligned} \mathcal{S} &= \{(p, q) \in \mathbb{R}^D \mid |q_s| \leq |q_L^*| \quad \forall s \in [0, t]\} \\ \mathcal{G} &= \{(p, q) \in \mathbb{R}^D \mid |q| < |q_L^*| \quad \text{and} \quad \exists \bar{t} \in (0, t) \text{ such that } |q_{\bar{t}}| > |q_L^*|\} \\ \mathcal{O} &= \{(p, q) \in \mathbb{R}^D \mid |q| \geq |q_L^*|\}. \end{aligned}$$

Since $|q_t| \geq |q_L^*| > Q + a$ for $q \in \mathcal{G}$ so that $\nabla W(\bar{q} - q_t) \equiv 0$ there, it is the case that we have

$$\begin{aligned} C_r(\mu_t^{\varepsilon,n}, \bar{q}) &= \int_{\mathcal{S} \cup \mathcal{O}} \theta_r(p_t) |\nabla W(\bar{q} - q_t)| R_t(p_t, q_t) d\mu_0(p, q) \\ &\leq B\mu_0(Q_L^*) + B \int_{\mathcal{S}} \theta_r(p_t) d\mu_0(p, q). \end{aligned} \tag{4.1}$$

Here in the last inequality we have used that $|\nabla W| \leq B$ and $|R_t| \leq 1$.

Since all measures under consideration have mass bounded by one, it is immediate that for all $t \in [0, T]$,

$$|\nabla W * \mu_t^{\varepsilon,n}| < B, \quad |W * \mu_t^{\varepsilon,n}| \leq B,$$

Therefore, for $(p, q) \in \mathcal{S}$, we have that by construction of Υ ,

$$\left| \frac{dp_s}{dt} \right| = |\nabla(\Phi + W * \mu_t^{\varepsilon,n})(q_s)| \leq M_L, \quad \forall s \in [0, t],$$

from which it directly follows that

$$|p_t| \leq M_L t + |p_0|.$$

On the other hand, for the trajectory to contribute to the last integral in (4.1) we must have $\theta_r(p_t) > 0$, so altogether we have

$$r - 1 \leq |p_t| \leq M_L t + |p_0|,$$

so that

$$|p_0| \geq r - 1 - M_L t = r^*,$$

yielding the conclusion. \square

REMARK 4.1. *Let us fix $t \in [0, T]$.*

(i) *In reference to the above lemma, for all $t \in [0, T]$ the entire bound now resides with μ_0 which is a particular (finite) measure. Thus we may choose L^* large so that the first term $\mu_0(Q_L^*)$ is small and then, by choosing r large, the second term can be made small. Not only is this uniform in t , we further note that the estimates of Lemma 4.1 are uniform in the discretization n and also ε , as the dynamical condition uniformly bounds the dynamics.*

(ii) *Let us set*

$$F_t^{\varepsilon, n} := \nabla W * \mu_t^{\varepsilon, n}, \quad F_t^\varepsilon = \nabla W * \mu_t^\varepsilon$$

and suppose that $\mu_t^{\varepsilon, n} \rightarrow \mu_t^\varepsilon$. We record that the above Lemma in particular implies that the hypothesis of Lemma 2.2 are satisfied and hence $F_t^{\varepsilon, n} \rightarrow F_t^\varepsilon$ uniformly on compact sets. (Recall that we have already established this via different means in the proof of Theorem 2.11).

Next we will acquire the required control on the time evolution of the (Hamiltonian) velocity fields. Let us denote by

$$v_t^{\varepsilon, n}(p, q) = [-\nabla(\Phi + W * \mu_{[\frac{t}{h_n}]h_n}^{\varepsilon, n})(q), p] := [-\nabla\Phi(q) + F_{t_n}^{\varepsilon, n}(q), p]$$

(where by slight abuse of notation, $t_n = t_n(t)$ is the nearest time discretization point) the relevant velocity field for the time discretized measures $\mu_t^{\varepsilon, n}$.

Suppose that $M_\alpha(\mu_0) < \infty$ for some $\alpha > 0$. Formally, from the deficient equation of continuity, we have

$$\partial_t F_t^{\varepsilon, n}(\bar{x}) = \int_{\mathbb{R}^D} (p \cdot \nabla^2 W(\bar{q} - q) - \varepsilon |v_t^{\varepsilon, n}(x)| |\nabla W(\bar{q} - q)|) d\mu_t^{\varepsilon, n}(x) =: A_{t,2}^{\varepsilon, n} - \varepsilon A_{t,1}^{\varepsilon, n},$$

where the above ∇^2 is notation for the matrix of second derivatives. This requires justification since, strictly speaking, W is not compactly supported in phase space. However, since $\varepsilon > 0$, we have exponential moments for $\mu_t^{\varepsilon, n}$ (see Proposition 2.4, (iii); here, in hindsight we may regard the $v_t^{\varepsilon, n}$ used in the construction of $\mu_t^{\varepsilon, n}$ as prescribed) and all relevant functions are C^1 so item (iii) of Remark 2.5 can be applied.

Recalling once again that for $n < \infty$ we may pullback to the initial measure, we rewrite the above as

$$A_{t,2}^{\varepsilon, n} = \int_{\mathbb{R}^D} p_t \cdot \nabla^2 W(\bar{q} - q_t) R_t^{\varepsilon, n}(p_t, q_t) d\mu_0(p, q)$$

and

$$A_{t,1}^{\varepsilon,n} = \int_{\mathbb{R}^D} |v_t^{\varepsilon,n}(p_t, q_t)| |\nabla W(\bar{q} - q_t)| R_t^{\varepsilon,n}(p_t, q_t) d\mu_0(p, q).$$

Let $\{q_L^*\}_{L=1}^\infty$ be the sequence of no-return points as in Hypothesis 3.2. We set $q_0^* = 0$. Given $q \in \mathbb{R}^d$, there exists a unique L such that $|q_L^*| \leq |q| < |q_{L+1}^*|$. Let us define

$$\mathcal{R}(q) = B + \max_{|q'| \leq |q_{L+1}^*|} |\nabla \Phi(q')| \quad \forall |q_L^*| \leq |q| < |q_{L+1}^*|.$$

For the potentials that we have in mind, under the assumption of an exponential moment for μ_0 , we certainly have that

$$\int_{\mathbb{R}^{2d}} \mathcal{R}(q) d\mu_0 < \infty. \quad (4.2)$$

LEMMA 4.2. *Let $Q > |q_1^*|$ and let $D_Q \subset \mathbb{R}^D$ be the ball of radius Q , centered at the origin. Let $\mu_t^{\varepsilon,n}$, $v_t^{\varepsilon,n}$ and μ_0 be as described and suppose that Equation (4.2) holds. (In particular, for the polynomially bounded potentials as discussed in Definition 2.10, and for μ_0 with an exponential moment, this is the case.) Then there exists a constant C_Q independent of ε, n such that*

$$\sup_{\bar{x}, t} \{|\nabla F_t^{\varepsilon,n}(\bar{x})| \mid \bar{x} \in D_Q, t \in [0, T]\} \leq C_Q \quad (4.3)$$

and

$$\sup_{\bar{x}, t} \{|\partial_t F_t^{\varepsilon,n}(\bar{x})| \mid \bar{x} \in D_Q, t \in [0, T]\} \leq C_Q. \quad (4.4)$$

Proof. Since $\nabla F_t^{\varepsilon,n} = \nabla^2 W * \mu_t^{\varepsilon,n}$, the first inequality of the lemma follows as $\nabla^2 W$ is bounded and $\mu_t^{\varepsilon,n}$ is a finite measure. It remains to show the second statement which requires a refinement of the proof of Lemma 4.1.

Choose $L > 0$ such that $|q_L^*| > Q + a$ and let \mathcal{S} , \mathcal{G} and \mathcal{O} be the sets defined in subsection 4.1 and corresponding to q_L^* . Each one of the above sets depends on ε, n as (p_t, q_t) is the flow associated to $v_t^{\varepsilon,n}$. But to alleviate the notation, we don't display these dependences. Let us provide preliminary estimates for the cases $(p, q) \in \mathcal{S}, \mathcal{G}, \mathcal{O}$:

If $(p, q) \in \mathcal{G}$ then $|q_t| > |q_L^*| > Q + a$ and so,

$$|\nabla W(\bar{q} - q_t)| |v_t(p_t, q_t)| = 0. \quad (4.5)$$

If $(p, q) \in \mathcal{S}$ then

$$|\dot{p}_s| \leq B + \max_{|q'| \leq |q_L^*|} |\nabla \Phi(q')| = \mathcal{R}(q_{L-1}^*)$$

for all $s \in [0, t]$ and so,

$$|v_t(p_t, q_t)|^2 = |p_t|^2 + |\dot{p}_t|^2 \leq (|p| + T\mathcal{R}(q_{L-1}^*))^2 + \mathcal{R}(q_{L-1}^*)^2.$$

Hence,

$$|\nabla W(\bar{q} - q_t)| |v_t(p_t, q_t)| \leq \|\nabla W\| \sqrt{(|p| + T\mathcal{R}(q_{L-1}^*))^2 + \mathcal{R}(q_{L-1}^*)^2}. \quad (4.6)$$

Finally, consider $(p, q) \in \mathcal{O}$ and let L_1 be such that $|q_{L_1}^*| \leq |q| < |q_{L_1+1}^*|$. Note that $L_1 \geq L$. Suppose that there exists $s \in [0, t)$ such that $|q_s| > |q_{L_1+1}^*|$. Let t_1 be the smallest such s . We have $|q_s| > |q_{L_1+1}^*|$ for all $s \in (t_1, t)$ and so, $\nabla W(\bar{q} - q_t) = 0$ for $s \in (t_1, t)$. If $|q_s| \leq |q_{L_1+1}^*|$ for all $s \in [0, t]$ then $|\dot{p}_s| \leq \mathcal{R}(q)$ for all $s \in [0, t]$ and so,

$$|p_t| \leq |p| + t\mathcal{R}(q).$$

We therefore have

$$|v_t(p_t, q_t)|^2 = |p_t|^2 + |\dot{p}_t|^2 \leq (|p| + T\mathcal{R}(q))^2 + \mathcal{R}(q)^2$$

and conclude that

$$|\nabla W(\bar{q} - q_t)| |v_t(p_t, q_t)| \leq \|\nabla W\| \sqrt{(|p| + T\mathcal{R}(q))^2 + \mathcal{R}(q)^2}. \quad (4.7)$$

Since by Equation (4.5) we need not consider $(p, q) \in \mathcal{G}$ we have

$$A_{t,1} = \int_{\mathcal{S} \cup \mathcal{O}} \nabla W(\bar{q} - q_t) |v_t(p_t, q_t)| R_t(p_t, q_t) d\mu_0(p, q).$$

We can now use Equations (4.2), (4.6) and (4.7) to conclude that

$$\sup_{t, |\bar{x}| \leq Q} |A_{t,1}(\bar{x})| =: C_{1,Q} < \infty. \quad (4.8)$$

Similar arguments yield

$$\sup_{t, |\bar{x}| \leq Q} |A_{t,2}(\bar{x})| =: C_{2,Q} < \infty. \quad (4.9)$$

Finally it is noted that these bounds are independent of ε, n since all estimates have been performed with the ‘‘reference’’ measure μ_0 , regardless of ε, n ; in particular, while the sets $\mathcal{G}, \mathcal{S}, \mathcal{O}$ themselves may depend on ε, n , once the position/momentum bounds have been obtained – independently of ε, n , the measures of these sets are all estimated by the full measure. This concludes the proof of the theorem. \square

The required ε tending to zero convergence of velocity field result now follows:

COROLLARY 4.2. *Let $K \subset \mathbb{R}^D$ be a compact set and suppose that $\mu_t^{\varepsilon, n} \rightharpoonup \mu_t$ sub-sequentially for some μ_t (by this we mean that along some sequence $(\varepsilon_k, n_k) \rightarrow (0, \infty)$ we have that $\mu_t^{\varepsilon_k, n_k} \rightharpoonup \mu_t$). Then $v_t^{\varepsilon, n}$ converges uniformly to $v_t := [-\nabla(\Phi + F_t)(q), p]$ on $K \times [0, T]$ (where $F_t = \nabla W * \mu_t$) and consequently,*

$$v_t^{\varepsilon, n} \mu_t^{\varepsilon, n} \rightharpoonup v_t \mu_t$$

in the sense of distribution.

Proof. Let first recall that $t_n = t_n(t)$ is the nearest time discretization point to t . It is sufficient to show that $F_{t_n}^{\varepsilon, n}$ converges to F_t uniformly (from this the distributional convergence immediately follows). Let us first observe that F_{t_n} is piecewise constant and (only) agrees with F_t at time discretization points.

Notwithstanding, we begin by showing that $F_t^{\varepsilon, n}$ converges to F_t uniformly. To this end, we have by Lemma 4.2 that the (phase) spatial and time derivatives are bounded and therefore the family $(F_t^{\varepsilon, n})$ is pre-compact on $C(K \times [0, T])$ by the Arzela–Ascoli theorem (and all functions in question are uniformly bounded) so there exists a subsequential limit \tilde{F}_t . On the other hand, inputting the tightness estimate

from Lemma 4.1 (in particular see Remark 4.1, (i)) into Lemma 2.2, we conclude that $\tilde{F}_t = F_t$, so in particular, we have convergence along the original (ε_k, n_k) sequence.

Finally, let us take into account the discretization: Since by Lemma 4.2

$$|F_{t_n}^{\varepsilon, n} - F_t| \leq |F_{t_n}^{\varepsilon, n} - F_{t_n}^{\varepsilon, n}| + |F_{t_n}^{\varepsilon, n} - F_t| \leq C_Q |t_n - t| + |F_{t_n}^{\varepsilon, n} - F_t|$$

(with $Q > 0$ such that $K \subset D_Q$) and $|t_n - t| \rightarrow 0$, as $n \rightarrow \infty$, the result follows. \square

Now we can repeat the logic of the proof of Theorem 2.11 to obtain existence of solution to the (limiting) Hamiltonian ODE:

THEOREM 4.3 (Existence of Solution to Hamiltonian ODE). *For fixed $0 < T < \infty$ and $\alpha_0 > 0$ let $\mu_0 \in M_{\alpha_0}$ denote some initial Borel measure on \mathbb{R}^D of finite total mass and let \mathcal{H} denote the Hamiltonian in Definition 2.10. Assume for simplicity that the total mass of μ_0 is 1. Then there exists a distributional limit of $(\mu_t^{\varepsilon, n})_{t \in [0, T]}$ along some subsequence (ε_k, n_k) , denoted $(\mu_t)_{t \in [0, T]}$ starting at μ_0 such that*

- (i) $t \rightarrow \mu_t \in \mathcal{M}$ is distributionally continuous and $M_0(\mu_t) \leq 1$ for $t \in [0, T]$.
- (ii) $(\mu_t)_{t \in [0, T]}$ satisfies the Hamiltonian ODE

$$\partial_t \mu_t + \nabla \cdot (J \nabla_W \mathcal{H}(\mu_t) \mu_t) = 0. \quad (4.10)$$

Proof. For $\varepsilon > 0$ we let $(\mu_t^{\varepsilon, n})_{t \in [0, T]}$ be the time discretized solutions from the proof of Theorem 2.11 with initial data μ_0 . It follows from the reasoning in the proof of Proposition 2.8 that we have a distributional limiting curve $(\mu_t)_{t \in [0, T]} \subset \mathcal{M}$ which is distributionally continuous; here we have taken $\mu_{t_k}^{\varepsilon, n_k} \rightarrow \mu_{t_k}$ for a dense set of times in $[0, T]$ and the rest of the argument is identical.

That $M_0(\mu_t) \leq 1$ follows, after a small argument, from distributional convergence (since $M_0(\mu_t^{\varepsilon, n}) \leq 1$ for all ε, n , by the same reasoning as used in the proof of Theorem 2.11). Finally, Corollary 4.2 gives the necessary convergence of the relevant velocity fields to yield the limiting dynamics (again we refer the reader to the proof of Theorem 2.11). \square

4.2. Closeness of Trajectories and Representation Formulae

In the ensuing subsection we will need stronger properties of μ_t^ε and associated trajectories. The key result in this subsection is a pullback formula for the measures μ_t^ε (Lemma 4.4). As a consequence we will immediately be able to extract a limiting Hamiltonian ODE statement which does not explicitly involve time discretization (Theorem 4.4). Let us first review the setting of Proposition 2.2:

Let $v_t^n : \mathbb{R}^D \times [0, T] \rightarrow \mathbb{R}^D$ be a sequence of Borel maps such that for each compact set $K \subset \mathbb{R}^D$, the f_K^n are in $L^\infty(0, T)$, where

$$f_K^n(t) = \sup_{x \in K} |v_t^n| + \text{Lip}(v_t^n, K).$$

Also let $v_t : \mathbb{R}^D \times [0, T] \rightarrow \mathbb{R}^D$ be another Borel map with

$$f_K(t) = \sup_{x \in K} |v_t| + \text{Lip}(v_t, K).$$

As in Proposition 2.2 we let e.g., $[0, \tau^n(x))$ be the maximal interval on which the ODE

$$\dot{X}_t^n = v_t^n(X_t^n), \quad X_0^n = x$$

admits a unique solution.

We begin with an abstract closeness of trajectories result.

LEMMA 4.3. *Let $(v_s^n : \mathbb{R}^D \times [0, t] \rightarrow \mathbb{R}^D \mid n \in \mathbb{N})$ be a sequence of velocity fields as described. Let $t > 0$ and suppose that v_s^n converges uniformly to some limiting velocity field v_s on $K \times [0, t]$ for any compact set $K \subset \mathbb{R}^D$. Suppose further that*

$$\sup_{n \in \mathbb{N}} \|f_K^n(t)\|_{L^\infty(0, t)} := f_K < \infty.$$

Let $L > 0$ and define

$$\mathbb{B}_t(L) = \{x \in \mathbb{R}^D \mid X(\cdot, x)[0, t] \subset D_L\},$$

where $D_L \subset \mathbb{R}^D$ denotes the (phase space) ball of radius L centered around the origin. Then given any $\delta > 0$, there exists $n_0(t, L, \delta)$ such that if $n \geq n_0$,

$$\sup_{x \in \mathbb{B}_t(L)} \sup_{s \in [0, t]} |X_s^n(x) - X_s(x)| \leq \delta.$$

Proof. Assume on the contrary that the conclusions do not hold. If so, there exists $\delta > 0$ and an increasing sequence $(n_k) \subset \mathbb{N}$, sequences $(x_k) \subset \mathbb{B}_t(L)$ and $(s_k) \subset [0, t]$ such that

$$|X_{s_k}^{n_k}(x_k) - X_{s_k}(x_k)| > 4\delta. \quad (4.11)$$

For each k set

$$\vartheta^k = \sup_{\tau \geq 0} \{\tau \mid |X_s^{n_k}(x_k) - X_s(x_k)| \leq 2\delta \text{ for all } s \in [0, \tau]\}.$$

Next choose $\sigma > 0$ such that

$$\sigma \exp(f_{D_{L+\delta}} t) < f_{D_{L+\delta}} \delta. \quad (4.12)$$

As (v_s^n) converges uniformly to v_s on $D_L \times [0, t]$ we may choose a positive integer k_0 so that

$$\sup_{D_L \times [0, t]} |v_s^{n_k} - v_s| < \sigma$$

for all $k \geq k_0$.

We claim that $\vartheta^k \geq t$ for $k \geq k_0$. Assume towards a contradiction that $\vartheta^k < t$. For almost every $s \in (0, \vartheta^k)$ we have

$$\begin{aligned} \frac{d}{ds} |X_s^{n_k}(x_k) - X_s(x_k)| &\leq |v_s^{n_k}(X_s^{n_k}(x_k)) - v_s(X_s(x_k))| \\ &\leq |v_s^{n_k}(X_s^{n_k}(x_k)) - v_s^{n_k}(X_s(x_k))| + |v_s^{n_k}(X_s(x_k)) - v_s(X_s(x_k))| \\ &\leq f_{D_{L+\delta}} |X_s^{n_k}(x_k) - X_s(x_k)| + \sigma. \end{aligned}$$

A Gronwall type integral inequality and Equation (4.12) yield

$$|X_s^{n_k}(x_k) - X_s(x_k)| \leq \frac{\sigma}{f_{D_{L+\delta}}} \cdot \exp(f_{D_{L+\delta}} s) < \delta.$$

This proves that $X_s^{n_k}(x_k, \cdot)[0, \vartheta^k]$ is contained in $D_{L+\delta}$. Hence the solution $X_s^{n_k}(x_k, \cdot)$ of the ODE can be extended to an interval of positive length $[\vartheta^k, \vartheta^k + a_k]$ such that by continuity

$$|X_s^{n_k}(x_k) - X_s(x_k)| \leq 2\delta$$

on $[0, \vartheta^k + a_k]$. This contradicts the maximality of ϑ^k and proves the claim. We eventually use the fact that $\vartheta^k \geq t$ for $k \geq k_0$ to contradict Equation (4.11). \square

The reasoning behind the above set of ideas now allows us to deduce a representation formula for μ_t^ε from the representation formula for $\mu_t^{\varepsilon, n}$, i.e., the measure at time t is expressible as the push-forward of μ_0 , augmented with the depreciation in mass provided by R_t^ε . Let us first recall that

$$\mathbb{S}_t^\varepsilon = \{x \in \mathbb{R}^D : \tau^\varepsilon(x) > t\},$$

where $\tau^\varepsilon(x)$ is such that the ODE $\dot{X}_t^\varepsilon(x) = v_t^\varepsilon(X_t^\varepsilon)$, $X_0^\varepsilon = \text{Id}$ has a unique solution on $[0, \tau^\varepsilon(x))$ (see Proposition 2.2).

LEMMA 4.4. *Let $\varepsilon > 0, t > 0$ be fixed and let $(\mu_s^\varepsilon)_{s \in [0, t]}$ be as constructed in Theorem 2.11. Then we have the representation formula: If $\varphi \in C_c^\infty(\mathbb{R}^D)$,*

$$\int_{\mathbb{R}^D} \varphi d\mu_t^\varepsilon = \int_{\mathbb{S}_t^\varepsilon} (\varphi \cdot R_t^\varepsilon) \circ X_t^\varepsilon d\mu_0,$$

where we recall that \mathbb{S}_t^ε is an open set, by Proposition 2.2, (ii).

Proof. The result essentially follows from Lemma 4.3 and the fact that since $\varepsilon > 0$, there is no ‘‘discontinuity at infinity’’. We first note that by distributional convergence and by the fact that for finite n we do have the representation formula, we have

$$\int_{\mathbb{R}^D} (\varphi \cdot R_t^{\varepsilon, n}) \circ X_t^{\varepsilon, n} d\mu_0 = \int_{\mathbb{R}^D} \varphi d\mu_t^{\varepsilon, n} \longrightarrow \int_{\mathbb{R}^D} \varphi d\mu_t^\varepsilon,$$

and therefore it is sufficient to establish that

$$\int_{\mathbb{R}^D} (\varphi \cdot R_t^{\varepsilon, n}) \circ X_t^{\varepsilon, n} d\mu_0 \longrightarrow \int_{\mathbb{S}_t^\varepsilon} (\varphi \cdot R_t^\varepsilon) \circ X_t^\varepsilon d\mu_0. \quad (4.13)$$

First we claim that $v_s^{\varepsilon, n}$ uniformly converges to v_s^ε on $K \times [0, t]$ for any compact set $K \subset \mathbb{R}^D$. Indeed, it is again sufficient to address the interaction term and the argument is essentially the same as the proof of Corollary 4.2; we remind the reader that the necessary estimates (namely Equations (4.3) and (4.4)) to ensure pre-compactness from Lemma 4.2 are uniform in n . We therefore may assume the conclusion of Lemma 4.3 for the trajectories $X_t^{\varepsilon, n}$ and X_t^ε .

To establish (4.13) we will divide into two cases:

1. Case: $x \in \mathbb{S}_t^\varepsilon$ (or $t < \tau^\varepsilon(x)$). In this case, for L sufficiently large, $x \in \mathbb{B}_t^\varepsilon(L)$ and therefore by Lemma 4.3 we have the pointwise limit

$$\lim_{n \rightarrow \infty} (R_t^{\varepsilon, n} \cdot \varphi) \circ X_t^{\varepsilon, n}(x) = \chi_{\mathbb{S}_t^\varepsilon} (R_t \cdot \varphi) \circ X_t^\varepsilon(x).$$

2. Case: $x \notin \mathbb{S}_t^\varepsilon$ (or $t \geq \tau^\varepsilon(x)$). Here we claim that pointwise the corresponding portion of the integrand in the left hand side of (4.13) converges to 0: Choose $r > 0$ arbitrary. Then choose A large enough so that $\exp(-\varepsilon A) < r$. Next, choose $\bar{t} < \tau^\varepsilon(x)$ such that $|X_{\bar{t}}^\varepsilon(x) - x| > 2A$. Since $\bar{t} < \tau^\varepsilon(x)$, by Lemma 4.3 there exists n_0 such that

$$|X_{\bar{t}}^{\varepsilon, n}(x) - X_{\bar{t}}^\varepsilon(x)| < A$$

for all $n \geq n_0$. Hence,

$$|X_{\bar{t}}^{\varepsilon, n}(x) - x| > A$$

and so,

$$R_t^{\varepsilon,n}(X_t^{\varepsilon,n}(x)) \leq \exp\left(-\varepsilon \int_0^{\bar{t}} |\dot{X}_s^{\varepsilon,n}| ds\right) \leq \exp\left(-\varepsilon |X_{\bar{t}}^{\varepsilon,n}(x) - x| ds\right) \leq \exp(-\varepsilon A) < r$$

for these n . This proves that

$$\limsup_{n \rightarrow \infty} R_t^{\varepsilon,n} \circ X_t^{\varepsilon,n}(x) \leq r.$$

Taking r to zero, we may conclude the case $x \notin \mathbb{S}_t^\varepsilon$.

Integrating and invoking the dominated convergence theorem now yields Equation (4.13). \square

We can now extract the limiting measures by taking ε to zero (along a sequence) directly:

THEOREM 4.4. *For fixed $0 < T < \infty$ and $\alpha_0 > 0$ let $\mu_0 \in M_{\alpha_0}$ denote some initial Borel measure on \mathbb{R}^D of finite total mass and let \mathcal{H} denote the Hamiltonian in Definition 2.10. Assume for simplicity that the total mass of μ_0 is 1. Let $(\mu_t^\varepsilon)_{t \in [0, T]}$ be as constructed in Theorem 2.11. Then there exists a distributional limit of $(\mu_t^\varepsilon)_{t \in [0, T]}$ along some subsequence (ε_k) , denoted $(\mu_t)_{t \in [0, T]}$ starting at μ_0 such that*

- (i) $t \rightarrow \mu_t \in \mathcal{M}$ is distributionally continuous and $M_0(\mu_t) \leq 1$ for $t \in [0, T]$.
- (ii) $(\mu_t)_{t \in [0, T]}$ satisfies the Hamiltonian ODE

$$\partial_t \mu_t + \nabla \cdot (J \nabla_W \mathcal{H}(\mu_t) \mu_t) = 0.$$

Proof. The representation formula from Lemma 4.4 allows us to adapt the proof of Corollary 4.2 for the measures $(\mu_t^\varepsilon)_{t \in [0, T]}$, yielding the requisite convergence of velocity fields. We remind the reader that once the representation formula has been acquired, the key ingredients for the proof of Corollary 4.2 are found in Lemma 4.2. The conclusion of this Lemma provided derivative bounds on the velocity fields – Equations (4.8) and (4.9) – and these bounds are uniform in (n and) ε . With these preparatory results in hand, the proof of Theorem 4.3 can be repeated *mutatis mutandis*. \square

We conclude this subsection with a result which turns out to be of no explicit use in the present work but may be of some independent interest: As an immediate corollary to the preceding ideas we can also deduce a closeness of trajectories result as ε tends to zero.

COROLLARY 4.5. *Let $L > 0, t > 0$ and consider μ_t^ε and trajectories given by the dynamics in Theorem 2.11. For $\varepsilon \geq 0$ we define*

$$\mathbb{B}_t^\varepsilon(L) = \{x \in \mathbb{R}^D \mid X^\varepsilon(\cdot, x)[0, t] \subset D_L\},$$

where D_L denotes the phase space ball of radius L centered around the origin. Suppose $\mu_t^{\varepsilon_k} \rightharpoonup \mu_t$. Then given any $\alpha > 0$, there exists $\varepsilon_0(t, L)$ such that if $\varepsilon \in (\varepsilon_k)$ and $\varepsilon < \varepsilon_0$, then

$$\sup_{x \in \mathbb{B}_t^\varepsilon(L)} \sup_{s \in [0, t]} |X_s^\varepsilon(x) - X_s(x)| < \delta.$$

In particular,

$$\mathbb{B}_t^\varepsilon(L) \subset \mathbb{B}_t^0(L + \alpha).$$

Proof. It is sufficient to verify the hypothesis of Lemma 4.3, which is immediate from Lemma 4.2 (here we reiterate that the relevant estimates in Equations (4.3) and (4.4) are uniform in ε ; c.f., proof of Theorem 4.4). We note that a further subsequence in ε is not required as the limit is uniquely specified by Lemma 2.2 (as was the case in the proof of Corollary 4.2). \square

4.3. Convergence of Mass

Here, we are in the setting of Theorem 4.4, and we wish to establish statements concerning convergence of (total) mass. In particular, for $\varepsilon_k \rightarrow 0$ and $\mu_t^{\varepsilon_k} \rightarrow \mu_t$ we will show that a limit exists for the finite ε -masses and in particular it agrees, a.e., with the mass of the limiting measure.

Since μ_t^ε has been constructed in Theorem 2.11 as the limit for the *narrow* convergence of a sequence $(\mu_t^{\varepsilon, n})$ such that $t \rightarrow \mu_t^{\varepsilon, n}(\mathbb{R}^D)$ is monotone nonincreasing, $t \rightarrow \mu_t^\varepsilon(\mathbb{R}^D)$ is monotone nonincreasing (which also follows from the fact that μ_t^ε satisfies Equation (2.2)). Unfortunately, in Theorem 4.4, μ_t is obtained as a limit of a subsequence of (μ_t^ε) only for the *vague* topology and so, the above simple argument does not apply. What is however obvious is that as μ_0^ε is independent of ε , $\mu_t(\mathbb{R}^D) \leq \mu_0(\mathbb{R}^D)$.

In light of the previous comments, we plan to first demonstrate that, at least under the dynamical condition, in the limiting measure the mass can only decrease in time. (That is, there cannot be particles returning from infinity.)

First, for expository ease, we will introduce *compact* regions of no return in phase space.

PROPOSITION 4.6. *Let $t > \bar{t} \geq 0$ and consider a trajectory $X_t = (p_t, q_t)$ satisfying the dynamics as in Theorem 2.11 such that $X_{\bar{t}}$ is in some $B_{L'} \times B_{L^*}$ for some $L' > 0$ and where L^* is as in Hypothesis 3.2 and remain in $\mathbb{R}^d \times B_{L^*} = \Omega_{L^*}$ up to time t . Then there is a L^* -dependent constant a_* such that uniformly in ε , for all $\tau \in [\bar{t}, t]$,*

$$|p_\tau| \leq a_*(t - \bar{t}) + |p_{\bar{t}}|.$$

Proof. Let us write $\tilde{F}_t^\varepsilon(q_t) = \nabla\Phi(q_t) + \nabla W * \mu_t^\varepsilon(q_t)$ and observe that since $|\nabla W|$ and $|\nabla\Phi|$ are both bounded in Ω_{L^*} , there is some L^* -dependent constant a_* such that $|F_t(q_t)| \leq a_*$. Taking into account the fact that, for all ε , the total mass of μ_t^ε can, without loss of generality, be assumed to be less than or equal to 1, we may explicitly choose

$$a_* = \sup_{q \in B_{L^*}} |\nabla\Phi| + |\nabla W|.$$

We have by the canonical equations that (uniformly in ε)

$$\frac{d}{ds} |p_s| \leq |\dot{p}_s| = |\tilde{F}_s(q_s)| \leq a_*,$$

where we have used that $|q_s| \leq |q_*| = L^*$ for all $0 \leq s \leq t$. The result follows by integration. \square

It is now clear that we may define phase space regions of no return:

DEFINITION 4.7. *Let $T > 0$ and let $(\mu_t^\varepsilon)_{t \in [0, T]}$ be given as in Theorem 2.11 and let $L^* \rightarrow \infty$ be the sequence as in Hypothesis 3.2. Let $\eta > 0$ be an arbitrary (small) number. Then we define*

$$\bar{\Omega}_{L^*}(t) = B_{L^* + (a_* + \eta)t} \times B_{L^*},$$

where a_\star is as in Proposition 4.6.

We then have

LEMMA 4.5. *Let $\bar{t} \in [0, T]$ be fixed. Under Hypothesis 3.2, for any trajectory $(p_{\bar{t}}, q_{\bar{t}}) \in \bar{\Omega}_{L^\star}(\bar{t})$ satisfying the dynamics as given in Theorem 2.11, it is the case that either*

$$(p_t, q_t) \in \bar{\Omega}_{L^\star}(t), \quad \text{for all } t \geq \bar{t},$$

or

$$|q_t| \rightarrow \infty$$

– either at some finite time or as $t \rightarrow \infty$. In particular, there is some time t_\star after which the radial speed is uniformly bounded away from zero: i.e., there exists some α and some $t_\star > \bar{t}$ such that

$$\frac{d|q_t|}{dt} \geq \alpha > 0, \quad \text{for all } t \geq t_\star.$$

Moreover, (p_t, q_t) exits $\bar{\Omega}_{L^\star}(t)$ on the $|q| = |q^\star|$ boundary.

Proof. This follows immediately from Lemma 3.1 and Proposition 4.6. Indeed if the space marginal never exceeds L^\star , then by Proposition 4.6 the momentum marginal remains within the stated bounds: Explicitly, as long as $q_{s'} \in B_{L^\star}$ for all $s' \in [\bar{t}, s]$, the corresponding momentum satisfies

$$|p_s| \leq L^\star + \bar{t}(a_\star + \eta) + (s - \bar{t})a_\star < L^\star + s(a_\star + \eta)$$

and hence $(p_s, q_s) \in \bar{\Omega}_{L^\star}(s)$. It follows that the only available exit is via the *position* space marginal and hence no possibility of return, by Lemma 2.1. \square

PROPOSITION 4.8. *Let $T > 0$ and let $(\mu_t)_{t \in [0, T]}$ be as obtained in Theorem 4.4 and let us denote by \mathbb{M}_t the total mass at time t : $\mathbb{M}_t = \mu_t(\mathbb{R}^D)$. Then \mathbb{M}_t is monotone non-increasing in t .*

Proof. Suppose $0 \leq t_1 < t_2 \leq T$. Let $\delta > 0$ and let us choose $L^\star > 0$ sufficiently large where L^\star is as described before so that

$$\mu_0((D_{L^\star})^c) < \delta$$

(where D_{L^\star} denotes the *phase space* ball of radius L^\star) and

$$\mu_{t_2}(\overline{(\bar{\Omega}_{L^\star}(t_2))^c}) < \delta.$$

Now we claim that for all ε ,

$$\mu_{t_1}^\varepsilon(\bar{\Omega}_{L^\star}(t_1)) \geq \mu_{t_2}^\varepsilon(\bar{\Omega}_{L^\star}(t_2)) - \delta. \quad (4.14)$$

In broad strokes, the argument proceeds as follows: By the representation formula in Lemma 4.4, we can decompose (at time t_2) the mass in $\bar{\Omega}_{L^\star}(t_2)$ into that which initiated, at $t=0$, from $\bar{\Omega}_{L^\star}(0)(=D_{L^\star})$ and that which did not. The latter clearly has μ_0 mass bounded by δ , while the former, path-wise, must be in the set $\bar{\Omega}_{L^\star}(t_1)$ at time t_1 , by the no-return condition stated in Lemma 4.5.

More explicitly, we claim that

$$D_{L^\star} \cap (X_{t_2}^\varepsilon)^{-1}(\bar{\Omega}_{L^\star}(t_2)) \subset D_{L^\star} \cap (X_{t_1}^\varepsilon)^{-1}(\bar{\Omega}_{L^\star}(t_1)). \quad (4.15)$$

Indeed, suppose $(p_0, q_0) \in D_{L^*}$ and $(p_{t_2}, q_{t_2}) \in \bar{\Omega}_{L^*}(t_2)$. If $|q_t| > L^*$ occurs for some $t \in (0, t_2)$, the no return condition would yield that $|q_{t_2}| > L^*$, which contradicts the fact that $(p_{t_2}, q_{t_2}) \in \bar{\Omega}_{L^*}(t_2)$. Consequently, $|q_t| \leq L^*$ for all $t \in [0, t_2]$ and so, $|dp_t/dt| \leq a_*$ for $t \in [0, t_1]$ which yields $(p_0, q_0) \in (X_{t_1}^\varepsilon)^{-1}(\bar{\Omega}_{L^*}(t_1))$.

The claimed inequality Equation (4.14) now basically follows from the above set containment along with the fact that R_t^ε is decreasing in t along each trajectory. More precisely, let $\varphi_k \in C_0$ with values in $[0, 1]$ and support in $\bar{\Omega}_{L^*}(t_2)$ be functions that satisfy

$$\mu_{t_2}^\varepsilon((\bar{\Omega}_{L^*}(t_2))^\circ) = \lim_{k \rightarrow \infty} \int_{\bar{\Omega}_{L^*}(t_2)} \varphi_k d\mu_{t_2}^\varepsilon.$$

(Such functions are readily constructed.) Then

$$\begin{aligned} \int_{\bar{\Omega}_{L^*}(t_2)} \varphi_k d\mu_{t_2}^\varepsilon &= \int_{(X_{t_2}^\varepsilon)^{-1}(\bar{\Omega}_{L^*}(t_2))} (\varphi_k \cdot R_{t_2}^\varepsilon) \circ X_{t_2}^\varepsilon d\mu_0 \\ &\leq \int_{D_{L^*} \cap (X_{t_2}^\varepsilon)^{-1}(\bar{\Omega}_{L^*}(t_2))} (\varphi_k \cdot R_{t_2}^\varepsilon) \circ X_{t_2}^\varepsilon d\mu_0 + \delta \end{aligned}$$

by our choice of D_{L^*} . Invoking the set containment in Equation (4.15), the above inequality can be continued as

$$\int_{\bar{\Omega}_{L^*}(t_2)} \varphi_k d\mu_{t_2}^\varepsilon \leq \int_{D_{L^*} \cap (X_{t_1}^\varepsilon)^{-1}(\bar{\Omega}_{L^*}(t_1))} (\varphi_k \cdot R_{t_2}^\varepsilon) \circ X_{t_2}^\varepsilon d\mu_0 + \delta.$$

Since $R_{t_2}^\varepsilon \circ X_{t_2}^\varepsilon \leq R_{t_1}^\varepsilon \circ X_{t_1}^\varepsilon$ the above becomes

$$\int_{\bar{\Omega}_{L^*}(t_2)} \varphi_k d\mu_{t_2}^\varepsilon \leq \int_{D_{L^*} \cap (X_{t_1}^\varepsilon)^{-1}(\bar{\Omega}_{L^*}(t_1))} (\varphi_k \circ X_{t_2}^\varepsilon) \cdot (R_{t_1}^\varepsilon \circ X_{t_1}^\varepsilon) d\mu_0 + \delta.$$

Next we observe that pushing forward to time t_1 , the second term in the product in the integrand together with $d\mu_0$ becomes $d\mu_{t_1}^\varepsilon$, the set of integration becomes $\bar{\Omega}_{L^*}(t_1) \cap X_{t_1}^\varepsilon(D_{L^*})$, and the integrand becomes $\varphi_k \circ X_{t_2-t_1}$:

$$\int_{\bar{\Omega}_{L^*}(t_2)} \varphi_k d\mu_{t_2}^\varepsilon \leq \int_{\bar{\Omega}_{L^*}(t_1) \cap X_{t_1}^\varepsilon(D_{L^*})} (\varphi_k \circ X_{t_2-t_1}) d\mu_{t_1}^\varepsilon + \delta \leq \mu_{t_1}^\varepsilon(\bar{\Omega}_{L^*}(t_1)) + \delta,$$

where the last inequality follows from the fact that $\varphi_k \leq 1$. Taking k to infinity, we conclude

$$\mu_{t_2}^\varepsilon((\bar{\Omega}_{L^*}(t_2))^\circ) \leq \mu_{t_1}^\varepsilon(\bar{\Omega}_{L^*}(t_1)) + \delta.$$

Since the above holds for all ε , we have by Equation (2.12) and the choice of L^* that

$$\begin{aligned} \mathbb{M}_{t_1} &\geq \mu_{t_1}(\bar{\Omega}_{L^*}(t_1)) \geq \limsup_\varepsilon \mu_{t_1}^\varepsilon(\bar{\Omega}_{L^*}(t_1)) \geq \limsup_\varepsilon \mu_{t_2}^\varepsilon((\bar{\Omega}_{L^*}(t_2))^\circ) - \delta \\ &\geq \liminf_\varepsilon \mu_{t_2}^\varepsilon((\bar{\Omega}_{L^*}(t_2))^\circ) - \delta \geq \mu_{t_2}((\bar{\Omega}_{L^*}(t_2))^\circ) - \delta \geq \mathbb{M}_{t_2} - 2\delta \end{aligned}$$

and the desired monotonicity follows by taking δ to zero. \square

Now we introduce a more quantitative version of the dynamical condition which can be understood as a requirement that the external potential diverges sufficiently fast near infinity:

HYPOTHESIS 4.9. *As in Section 3, we consider dynamics given by the Hamiltonian*

$$H(p, q, t) = \frac{1}{2}|p|^2 + \Phi(q) + \Psi(t, q), \quad (4.16)$$

where $|\nabla\Psi(t, q)| < B, \forall t \geq 0, q \in \mathbb{R}^d$ (so that in particular we may take, e.g., $\Psi(t, q) = (W * \mu_t^\varepsilon)(q_t)$). Recall that Hypothesis 3.2 concerned the existence of spherically symmetric bounding potentials Υ such that $\Upsilon(q) < \Upsilon(q_L^*)$ for all $|q| > |q_L^*|$.

Here we are concerned with pairs of position space rings L and $\ell(L)$ such that $\ell(L) < L$ (not necessarily adjacent). Let $t > 0$ be essentially arbitrary and let us consider trajectories of particles operating under Υ -dynamics which exit B_L at time t , having at some earlier time exited B_ℓ

$$\tilde{E}_L(t) := \{q_s \mid q_t \in \partial B_L, q_{t'} \in B_{\ell(L)} \text{ for some } t' < t.\}$$

Obviously, for some t 's, the sets $\tilde{E}_L(t)$ are non-empty. For $\tilde{E}_L(t) \neq \emptyset$ we may define

$$\tilde{\vartheta}_L(t) = \sup\{\tau \mid q(s) \in \tilde{E}_L(t), |q_{t+\tau}| < \infty\}.$$

And, if $\tilde{E}_L(t) = \emptyset$ – e.g., if Υ is very repulsive and t is too large – then we may, for convenience, define $\tilde{\vartheta}_L(t) = 0$. Finally we define

$$\tilde{\tau}_L = \sup_t \tilde{\vartheta}_L(t).$$

We take as a hypothesis the existence of a sequence $(L, \ell(L))$ with $\ell(L) \rightarrow \infty$ such that

$$\lim_{L \rightarrow \infty} \tilde{\tau}_L = 0.$$

REMARK 4.10. *Following along the lines of the discussions in Remark 3.3, it is readily derived that if the bounding potential Υ satisfies power law upper and lower bounds of the form*

$$D_2|q|^{d_2} \leq |\Upsilon| \leq D_1|q|^{d_1}$$

with d_1, d_2 larger than 2 then, if Hypothesis 3.2 is satisfied, then the stronger Hypothesis 4.9 also holds.

PROPOSITION 4.11. *Let $t > 0$ be arbitrary and consider Hamiltonian dynamics according to Equation (4.16). Suppose Hypothesis 4.9 holds. Let us define the phase space “escape times” τ_L by analogy to the above with B_L 's etc., replaced by the appropriate $\bar{\Omega}_L$'s providing us with (untilded) versions of $\tilde{E}_L(t)$ and $\tilde{\vartheta}_L(t)$.*

Then we have

$$\lim \tau_L \rightarrow 0 \quad \text{as } L \rightarrow \infty.$$

Proof. This is immediate from Lemma 4.5 which ensures that when particles exit $\bar{\Omega}_L(t)$, they do so via the position space barrier and the fact (as can be seen from e.g., Equation (3.5)) that the actual radial momentum is bounded by that provided by the Υ -dynamics. \square

REMARK 4.12. *We remark that for finite ε , the quantity τ_L is a universal bound for the non-existence of trajectories that are in $\bar{\Omega}_\ell(t')$ at time t' and exiting $\bar{\Omega}_L(t)$ at time*

t. Indeed, all dynamics are bounded by the dynamics driven by the potential Υ which is, by fiat, uniform in ε .

THEOREM 4.13. *Suppose Hypothesis 4.9 holds and suppose that $\mu_t^{\varepsilon_k} \rightharpoonup \mu_t$ as in Theorem 4.4. Then it is the case that for almost every $t \in [0, T]$,*

$$\mathbb{M}_t = \lim_{\varepsilon_k \rightarrow 0} \mathbb{M}_t^{\varepsilon_k}.$$

More specifically the above convergence holds at all points of continuity of \mathbb{M}_t .

Proof. Let us denote

$$\mathbb{M}_t^- = \lim_{t' \nearrow t} \mathbb{M}_{t'}, \quad \mathbb{M}_t^+ = \lim_{t' \searrow t} \mathbb{M}_{t'}$$

and

$$\mathbb{M}_t^\bullet = \limsup_{\varepsilon_k \rightarrow 0} \mathbb{M}_t^{\varepsilon_k}, \quad \mathbb{M}_t^\circ = \liminf_{\varepsilon_k \rightarrow 0} \mathbb{M}_t^{\varepsilon_k}.$$

It is clear that $\mathbb{M}_t^\circ \leq \mathbb{M}_t^\bullet$ and the monotonicity result of \mathbb{M}_t established in Proposition 4.8 gives that $\mathbb{M}_t^+ \leq \mathbb{M}_t^-$. We will establish that in fact

$$\mathbb{M}_t^+ \leq \mathbb{M}_t^\circ \leq \mathbb{M}_t^\bullet \leq \mathbb{M}_t^-$$

from which the result follows. In particular (although (sub)subsequential limits are already guaranteed by the monotonicity of the $\mathbb{M}_t^{\varepsilon_k}$) this establishes, a.e., the existence of the limit for $\mathbb{M}_t^{\varepsilon_k}$ at points of continuity of \mathbb{M}_t . We will separate the proof into two claims.

Claim. $\mathbb{M}_t^+ \leq \mathbb{M}_t^\circ$:

Let $\delta > 0$ be arbitrary, and let $L > 0$ be such that $\mu_t(\overline{D_L^c}) < \delta$, where D_L denotes a *phase space* ball of radius L . Then, from weak* convergence (see Equation (2.12))

$$\mathbb{M}_t \leq \mu_t(D_L^\circ) + \delta \leq \liminf_{\varepsilon_k \rightarrow 0} \mu_t^{\varepsilon_k}(D_L) + \delta \leq \mathbb{M}_t^\circ + \delta$$

and the claim follows. (Note that this shows that a mass convergence result is immediate in the absence of the interaction W , since then all trajectories X_t^ε 's are the same and the masses \mathbb{M}_t^ε are monotonically *increasing* as $\varepsilon \rightarrow 0$.)

Claim. $\mathbb{M}_t^\bullet \leq \mathbb{M}_t^-$:

Let $\delta > 0$ and let $\ell := \ell(L)$ be from the hypothesized sequence in Hypothesis 4.9 such that

$$\mu_0\left(\overline{(\bar{\Omega}_\ell(0))^c}\right) < \delta.$$

Next given any $\varepsilon > 0$ we let $L_\varepsilon > 0$ be such that

$$\mu_t^\varepsilon\left(\overline{(\bar{\Omega}_{L_\varepsilon}(t))^c}\right) < \delta.$$

Let us now consider the time $t - \tau_L$ with τ_L as in Proposition 4.11. Then we claim that

$$\mu_t^\varepsilon(\bar{\Omega}_{L_\varepsilon}(t)) \leq \mu_{t-\tau_L}^\varepsilon(\bar{\Omega}_L(t-\tau_L)) + \delta.$$

On the level of heuristics (and neglecting for the time being the (beneficial) effect of reduction in mass afforded by R_t^ε) the above display can be understood as follows:

First we observe that by our choice of ℓ we may restrict attention to mass that *initiated* in D_ℓ . Now all of this mass that is in $\bar{\Omega}_L(t)$ at time t is certainly in $\bar{\Omega}_L(t')$ for $t' < t$ since L is a ring of no return (this is the same reasoning as used in the proof of Proposition 4.8) and in particular this applies to $t' = t - \tau_L$. As for the mass in $\bar{\Omega}_{L_\varepsilon}(t) \setminus \bar{\Omega}_L(t)$, we note that if the representative particles had already left $\bar{\Omega}_L(t - \tau_L)$ before time $t - \tau_L$ then by time t they would be (well) beyond $\bar{\Omega}_{L_\varepsilon}(t)$, by the definition of τ_L ; here we are specifically employing the hypothesized properties of (ℓ, L) .

The actual proof proceeds as follows: Let $\eta > 0$ and let φ_η be a continuous function such $\varphi_\eta = 1$ on $\bar{\Omega}_{L_\varepsilon}(t)$ and $\varphi_\eta = 0$ on $(\bar{\Omega}_{L_\varepsilon + \eta}(t))^c$. We have then by the representation formula in Lemma 4.4

$$\begin{aligned} \mu_t^\varepsilon(\bar{\Omega}_{L_\varepsilon}(t)) &\leq \int_{\mathbb{R}^D} \varphi_\eta d\mu_t^\varepsilon = \int_{\mathbb{R}^D} (\varphi_\eta \cdot R_t^\varepsilon) \circ X_t^\varepsilon d\mu_0 \\ &\leq \int_{(X_t^\varepsilon)^{-1}(\bar{\Omega}_{L_\varepsilon + \eta}(t)) \cap D_\ell} (\varphi_\eta \cdot R_t^\varepsilon) \circ X_t^\varepsilon d\mu_0 + \delta. \end{aligned}$$

Now, we claim, we have the set containment

$$D_\ell \cap (X_t^\varepsilon)^{-1}(\bar{\Omega}_{L_\varepsilon + \eta}(t)) \subset D_\ell \cap (X_{t-\tau_L}^\varepsilon)^{-1}(\bar{\Omega}_L(t - \tau_L)).$$

Indeed, following the reasoning in Equation (4.15) we certainly have that the left hand side is contained in $D_\ell \cap (X_{t-\tau_L}^\varepsilon)^{-1}(\bar{\Omega}_{L_\varepsilon + \eta}(t - \tau_L))$, so it remains to establish the stronger statement that we can shrink down to spatial scale L . Suppose then that $(p_0, q_0) \in D_\ell$ and

$$(p_{t-\tau_L}, q_{t-\tau_L}) \in \bar{\Omega}_{L_\varepsilon + \eta}(t - \tau_L) \setminus \bar{\Omega}_L(t - \tau_L).$$

Then the trajectory was, initially, in $\bar{\Omega}_\ell(0)$ and at some time s' which is earlier than $t - \tau_L$ had exited $\bar{\Omega}_L(s')$. It follows by the definition of τ_L that at some point before time t , the trajectory had ceased to exist (gone to infinity) and therefore it is certainly not in $\bar{\Omega}_{L_\varepsilon + \eta}(t)$.

Continuing and using the representation formula from Lemma 4.4 again, we now have

$$\begin{aligned} \mu_t^\varepsilon(\bar{\Omega}_{L_\varepsilon}(t)) &\leq \int_{(X_{t-\tau_L}^\varepsilon)^{-1}(\bar{\Omega}_L(t - \tau_L)) \cap D_\ell} (\varphi_\eta \cdot R_t^\varepsilon) \circ X_t^\varepsilon d\mu_0 + \delta \\ &\leq \int_{\bar{\Omega}_L(t - \tau_L)} \varphi_\eta d\mu_{t-\tau_L}^\varepsilon + \delta \\ &\leq \mu_{t-\tau_L}^\varepsilon(\bar{\Omega}_L(t - \tau_L)) + \delta \end{aligned}$$

as claimed.

Using the inequality established above and the choice of L_{ε_k} we have

$$\mathbb{M}_t^{\varepsilon_k} \leq \mu_t^{\varepsilon_k}(\bar{\Omega}_{L_{\varepsilon_k}}(t)) + \delta \leq \mu_{t-\tau_L}^{\varepsilon_k}(\bar{\Omega}_L(t - \tau_L)) + 2\delta.$$

Taking the limsup and recalling again Equation (2.12), we arrive at

$$\mathbb{M}_t^\bullet \leq \mu_{t-\tau_L}(\bar{\Omega}_L(t - \tau_L)) + 2\delta \leq \mathbb{M}_{t-\tau_L} + 2\delta.$$

The result follows by taking L to infinity. \square

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